intersil

DATASHEET

Dual, 128-Tap, Low Voltage Digitally Controlled Potentiometer (XDCP™)

ISL23428

The ISL23428 is a volatile, low voltage, low noise, low power, 128-tap, dual digitally controlled potentiometer (DCP) with an SPI Bus[™] interface. It integrates two DCP cores, wiper switches and control logic on a monolithic CMOS integrated circuit.

Each digitally controlled potentiometer is implemented with a combination of resistor elements and CMOS switches. The position of the wipers are controlled by the user through the SPI bus interface. Each potentiometer has an associated volatile Wiper Register (WRi, i = 0, 1) that can be directly written to and read by the user. The contents of the WRi controls the position of the wiper. When powered on, the wiper of each DCP will always commence at mid-scale (64 tap position).

The low voltage, low power consumption, and small package of the ISL23428 make it an ideal choice for use in battery operated equipment. In addition, the ISL23428 has a V_{LOGIC} pin allowing down to 1.2V bus operation, independent from the V_{CC} value. This allows for low logic levels to be connected directly to the ISL23428 without passing through a voltage level shifter.

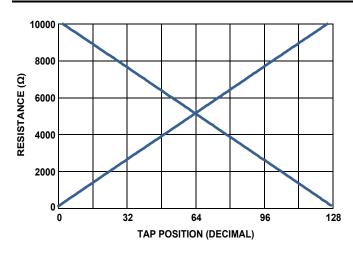
The DCP can be used as a three-terminal potentiometer or as a two-terminal variable resistor in a wide variety of applications including control, parameter adjustments, and signal processing.

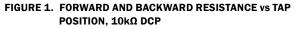
Applications

- · Power supply margining
- Trimming sensor circuits
- · Gain adjustment in battery powered instruments
- · RF power amplifier bias compensation

Features

- Two potentiometers per package
- 128 resistor taps
- 10k Ω , 50k Ω or 100k Ω total resistance
- SPI serial interface
 - No additional level translator for low bus supply
 - Daisy Chaining of multiple DCPs
- · Power supply
 - V_{CC} = 1.7V to 5.5V analog power supply
 - V_{LOGIC} = 1.2V to 5.5V SPI bus/logic power supply
- Maximum supply current without serial bus activity (standby)
 - 4µA @ V_{CC} and V_{LOGIC} = 5V
 - 1.7µA @ V_{CC} and V_{LOGIC} = 1.7V
- Shutdown Mode
 - Forces the DCP into an end-to-end open circuit and RWi is connected to RLi internally
 - Reduces power consumption by disconnecting the DCP resistor from the circuit
- Wiper resistance: 70Ω typical @ V_{CC} = 3.3V
- · Power-on preset to mid-scale (64 tap position)
- Extended industrial temperature range: -40°C to +125°C
- 14 Ld TSSOP or 16 Ld UTQFN packages
- Pb-free (RoHS compliant)





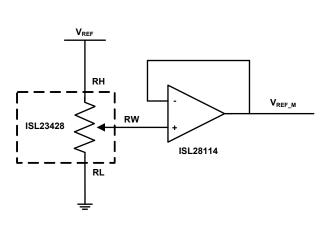
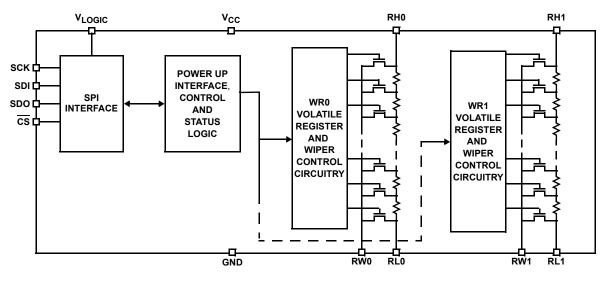


FIGURE 2. VREF ADJUSTMENT

Block Diagram



Pin Descriptions

SYMBOL

GND

VLOGIC

DESCRIPTION

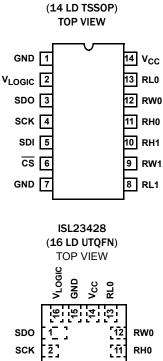
UTQFN

5, 6, 15

16

2

Pin Configurations



10 RH1

RL1

RW1

ISL23428

TSSOP 1,7

3 1 SDO Logic Pin - Serial bus data output (configurable) 4 2 SCK Logic Pin - Serial bus clock input 5 3 SDI Logic Pin - Serial bus data input 6 4 CS Logic Pin - Active low chip select RL1 DCP1 "low" terminal 8 8 9 9 RW1 DCP1 wiper terminal 10 RH1 10 DCP1 "high" terminal RH0 DCP0 "high" terminal 11 11 12 12 RW0 DCP0 wiper terminal 13 RL0 DCP0 "low" terminal 13 14 14 V_{CC} Analog power supply. Range 1.7V to 5.5V 7 NC Not Connected -

Ground pin

SPI bus/logic supply Range 1.2V to 5.5V

SDI 3

cs

∡

1011 ñ GND GND

Ordering Information

| PART NUMBER (Note 4) | PART MARKING | RESISTANCE OPTION (kΩ) | TEMP RANGE (°C) | PACKAGE (RoHS Compliant) | PKG. DWG. # |
|---|-----------------|------------------------------|--------------------|-----------------------------|----------------|
| ISL23428TFVZ (Note 2) | 23428 TFVZ | 100 | -40 to +125 | 14 Ld TSSOP | M14.173 |
| ISL23428TFVZ-T7A (Notes 1, 2) | 23428 TFVZ | 100 | -40 to +125 | 14 Ld TSSOP | M14.173 |
| ISL23428TFVZ-TK (Notes 1, 2) | 23428 TFVZ | 100 | -40 to +125 | 14 Ld TSSOP | M14.173 |
| ISL23428UFVZ (Note 2) (No longer available, recommended replacement: ISL23428TFRUZ-TK) | 23428 UFVZ | 50 | -40 to +125 | 14 Ld TSSOP | M14.173 |
| ISL23428UFVZ-T7A (Notes 1, 2) (No longer available, recommended replacement: ISL23428TFRUZ-TK) | 23428 UFVZ | 50 | -40 to +125 | 14 Ld TSSOP | M14.173 |
| ISL23428UFVZ-TK (Notes 1, 2) (No longer available, recommended replacement: ISL23428TFRUZ-TK) | 23428 UFVZ | 50 | -40 to +125 | 14 Ld TSSOP | M14.173 |
| ISL23428WFVZ (Note 2) | 23428 WFVZ | 10 | -40 to +125 | 14 Ld TSSOP | M14.173 |
| ISL23428WFVZ-T7A (Notes 1, 2) | 23428 WFVZ | 10 | -40 to +125 | 14 Ld TSSOP | M14.173 |
| ISL23428WFVZ-TK (Notes 1, 2) | 23428 WFVZ | 10 | -40 to +125 | 14 Ld TSSOP | M14.173 |
| ISL23428TFRUZ-T7A (Notes 1, 3) | GBR | 100 | -40 to +125 | 16 Ld 2.6x1.8 UTQFN | L16.2.6x1.8A |
| ISL23428TFRUZ-TK (Notes 1, 3) | GBR | 100 | -40 to +125 | 16 Ld 2.6x1.8 UTQFN | L16.2.6x1.8A |
| ISL23428UFRUZ-T7A (Notes 1, 3) (No longer available, recommended replacement: ISL23428TFRUZ-TK) | GBP | 50 | -40 to +125 | 16 Ld 2.6x1.8 UTQFN | L16.2.6x1.8A |
| ISL23428UFRUZ-TK (Notes 1, 3) (No longer available, recommended replacement: ISL23428TFRUZ-TK) | GBP | 50 | -40 to +125 | 16 Ld 2.6x1.8 UTQFN | L16.2.6x1.8A |
| ISL23428WFRUZ-T7A (Notes 1, 3) | GBN | 10 | -40 to +125 | 16 Ld 2.6x1.8 UTQFN | L16.2.6x1.8A |
| ISL23428WFRUZ-TK (Notes 1, 3) | GBN | 10 | -40 to +125 | 16 Ld 2.6x1.8 UTQFN | L16.2.6x1.8A |

NOTES:

1. Please refer to TB347 for details on reel specifications.

2. These Intersil Pb-free plastic packaged products employ special Pb-free material sets, molding compounds/die attach materials, and 100% matte tin plate plus anneal (e3 termination finish, which is RoHS compliant and compatible with both SnPb and Pb-free soldering operations). Intersil Pb-free products are MSL classified at Pb-free peak reflow temperatures that meet or exceed the Pb-free requirements of IPC/JEDEC J STD-020.

3. These Intersil Pb-free plastic packaged products employ special Pb-free material sets; molding compounds/die attach materials and NiPdAu plate-e4 termination finish, which is RoHS compliant and compatible with both SnPb and Pb-free soldering operations. Intersil Pb-free products are MSL classified at Pb-free peak reflow temperatures that meet or exceed the Pb-free requirements of IPC/JEDEC J STD-020

4. For Moisture Sensitivity Level (MSL), please see device information page for ISL23428. For more information on MSL please see techbrief TB363.

Absolute Maximum Ratings

Supply Voltage Range

| V _{CC} 0.3V to 6.0V |
|---|
| V _{LOGIC} |
| Voltage on Any DCP Terminal Pin |
| Voltage on Any Digital Pins |
| Wiper current IW (10s) ±6mA |
| ESD Rating |
| Human Body Model (Tested per JESD22-A114E)4.5kV |
| CDM Model (Tested per JESD22-A114E) 1kV |
| Machine Model (Tested per JESD22-A115-A) |
| Latch Up (Tested per JESD-78B; Class 2, Level A) 100mA @ +125°C |
| • • • |

Thermal Information

| Thermal Resistance (Typical) | θ _{JA} (°C/W) | θ _{JC} (°C/W) |
|---|------------------------|------------------------|
| 14 Ld TSSOP Package (Notes 5, 6) | 112 | 40 |
| 16 Ld UTQFN Package (Notes 5, 6) | 110 | 64 |
| Maximum Junction Temperature (Plastic Pac | kage) | +150°C |
| Storage Temperature Range | 6 | 5°C to +150°C |
| Pb-Free Reflow Profile | | . see link below |
| http://www.intersil.com/pbfree/Pb-FreeRe | eflow.asp | |

Recommended Operating Conditions

| Temperature40 | °C to +125°C |
|-----------------------------------|----------------------|
| V _{CC} Supply Voltage | 1.7V to 5.5V |
| V _{LOGIC} Supply Voltage | 1.2V to 5.5V |
| DCP Terminal Voltage | 0 to V _{CC} |
| Max Wiper Current | ±3mA |

CAUTION: Do not operate at or near the maximum ratings listed for extended periods of time. Exposure to such conditions may adversely impact product reliability and result in failures not covered by warranty.

NOTES:

- 5. θ_{JA} is measured with the component mounted on a high effective thermal conductivity test board in free air. See Tech Brief <u>TB379</u> for details.
- 6. For $\theta_{\text{JC}},$ the "case temp" location is the center top of the package.

Analog Specifications V_{CC} = 2.7V to 5.5V, V_{LOGIC} = 1.2V to 5.5V over recommended operating conditions unless otherwise stated. Boldface limits apply over the operating temperature range, -40°C to +125°C.

| SYMBOL | PARAMETER | TEST CONDITIONS | MIN (Note 19) | TYP (Note 7) | MAX (Note 19) | UNITS |
|-----------------------------------|--|--|------------------|-----------------|------------------|----------------|
| R _{TOTAL} | RH to RL Resistance | W option | | 10 | | kΩ |
| | | U option | | 50 | | kΩ |
| | | T option | | 100 | | kΩ |
| | RH to RL Resistance Tolerance | | -20 | ±2 | +20 | % |
| | End-to-End Temperature Coefficient | W option | | 125 | | ppm/°C |
| | | U option | | 65 | | ppm/°C |
| | | T option | | 45 | | ppm/°C |
| V _{RH} , V _{RL} | DCP Terminal Voltage | V _{RH} or V _{RL} to GND | 0 | | V _{CC} | v |
| R _W | Wiper Resistance | RH - floating, V_{RL} = 0V, force I _W current to the wiper, I _W = (V _{CC} - V _{RL})/R _{TOTAL} , V _{CC} = 2.7V to 5.5V | | 70 | 200 | Ω |
| | | V _{CC} = 1.7V | | 580 | | Ω |
| $C_{H}/C_{L}/C_{W}$ | Terminal Capacitance | See "DCP Macro Model" on page 9 | | 32/32/32 | | pF |
| ILkgDCP | Leakage on DCP Pins | Voltage at pin from GND to V _{CC} | -0.4 | <0.1 | 0.4 | μA |
| Noise | Resistor Noise Density | Wiper at middle point, W option | | 16 | | nV/\sqrt{Hz} |
| | | Wiper at middle point, U option | | 49 | | nV/\sqrt{Hz} |
| | | Wiper at middle point, T option | | 61 | | nV/\sqrt{Hz} |
| Feed Thru | Digital Feed-through from Bus to Wiper | Wiper at middle point | | -65 | | dB |
| PSRR | Power Supply Reject Ratio | Wiper output change if V _{CC} change ±10%; wiper at middle point | | -75 | | dB |

| Analog Specifications | V_{CC} = 2.7V to 5.5V, V_{LOGIC} = 1.2V to 5.5V over recommended operating conditions unless otherwise stated. |
|-----------------------|--|
| | ng temperature range, -40°C to +125°C. (Continued) |

| SYMBOL | PARAMETER | TEST CONDITIONS | MIN (Note 19) | TYP (Note 7) | MAX (Note 19) | UNITS |
|-------------------------------|---|---|------------------|-----------------|------------------|-----------------|
| VOLTAGE DI | IVIDER MODE (OV @ RL; V _{CC} @ RH; mea | asured at RW, unloaded) | | | | |
| INL (Note 12) | Integral Non-linearity, Guaranteed Monotonic | W option | -0.5 | ±0.15 | +0.5 | LSB (Note 8) |
| | | U, T option | -0.5 | ±0.15 | +0.5 | LSB (Note 8) |
| DNL (Note 11) | Differential Non-linearity, Guaranteed Monotonic | W option | -0.5 | ±0.15 | +0.5 | LSB (Note 8) |
| | | U, T option | -0.5 | ±0.15 | +0.5 | LSB (Note 8) |
| FSerror (Note 10) | Full-scale Error | W option | -3 | -1.5 | 0 | LSB (Note 8) |
| | | U, T option | -1.5 | -0.9 | 0 | LSB (Note 8) |
| ZSerror (Note 9) | Zero-scale Error | W option | 0 | 1.5 | 3 | LSB (Note 8) |
| | | U, T option | 0 | 0.9 | 1.5 | LSB (Note 8) |
| Vmatch (Note 21) | DCP to DCP Matching | DCPs at same tap position, same voltage at all RH terminals, and same voltage at all RL terminals | -2 | ±0.5 | 2 | LSB (Note 8) |
| тс _v | Ratiometric Temperature Coefficient | W option, Wiper Register set to 40 hex | | 8 | | ppm/°C |
| (Note 13) | | U option, Wiper Register set to 40 hex | | 4 | | ppm/°C |
| | | T option, Wiper Register set to 40 hex | | 2.3 | | ppm/°C |
| tLS_Settling | Large Signal Wiper Settling Time | From code 0 to 7F hex, measured from 0 to 1 LSB settling of the wiper | | 300 | | ns |
| f _{cutoff} | -3dB Cutoff Frequency | Wiper at middle point W option | | 1200 | | kHz |
| | | Wiper at middle point U option | | 250 | | kHz |
| | | Wiper at middle point T option | | 120 | | kHz |
| RHEOSTAT | MODE (Measurements between RW an | d RL pins with RH not connected, or betw | veen RW and | RH with RL n | ot connected) |) |
| R _{INL} (Note 17) | Integral Non-Linearity, Guaranteed Monotonic | W option; V _{CC} = 2.7V to 5.5V | -1.0 | ±0.5 | +1.0 | MI (Note 14 |
| | | W option; V _{CC} = 1.7V | | 4 | | MI (Note 14 |
| | | U, T option; V _{CC} = 2.7V to 5.5V | -0.5 | ±0.15 | +0.5 | MI (Note 14 |
| | | U, T option; V _{CC} = 1.7V | | 1 | | MI (Note 14 |
| R _{DNL} (Note 16) | Differential Non-Linearity, Guaranteed Monotonic | W option; V _{CC} = 2.7V to 5.5V | -0.5 | ±0.15 | +0.5 | MI (Note 14 |
| | | W option; V _{CC} = 1.7V | | ±0.4 | | MI (Note 14 |
| | | U, T option; V _{CC} = 2.7V to 5.5V | -0.5 | ±0.15 | +0.5 | MI (Note 14 |
| | | U, T option; V _{CC} = 1.7V | | ±0.4 | | MI (Note 14 |

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Analog Specifications V_{CC} = 2.7V to 5.5V, V_{LOGIC} = 1.2V to 5.5V over recommended operating conditions unless otherwise stated. Boldface limits apply over the operating temperature range, -40 °C to +125 °C. (Continued)

| SYMBOL | PARAMETER | TEST CONDITIONS | MIN (Note 19) | TYP (Note 7) | MAX (Note 19) | UNITS |
|----------------------------------|---|---|------------------|-----------------|------------------|-----------------|
| R _{offset} (Note 15) | Offset, Wiper at 0 Position | W option; V _{CC} = 2.7V to 5.5V | 0 | 1.8 | 3 | MI (Note 14) |
| | | W option; V _{CC} = 1.7V | | 3 | | MI (Note 14) |
| | U, T option; V _{CC} = 2.7V to 5.5V | 0 | 0.3 | 1 | MI (Note 14) | |
| | | U, T option; V _{CC} = 1.7V | | 0.5 | | MI (Note 14) |
| Rmatch (Note 22) | DCP to DCP Matching | Any two DCPs at the same tap position with the same terminal voltages | -2 | ±0.5 | 2 | LSB (Note 8) |
| TCR (Note 18) | Resistance TemperatureCoefficient | W option; Wiper register set between 19 hex and 7F hex | | 170 | | ppm/°C |
| | | U option; Wiper register set between 19 hex and 7F hex | | 80 | | ppm/°C |
| | | T option; Wiper register set between 19 hex and 7F hex | | 50 | | ppm/°C |

Operating Specifications V_{CC} = 2.7V to 5.5V, V_{LOGIC} = 1.2V to 5.5V over recommended operating conditions unless otherwise stated. Boldface limits apply over the operating temperature range, -40°C to +125°C.

| SYMBOL | PARAMETER | TEST CONDITIONS | MIN (Note 19) | TYP (Note 7) | MAX (Note 19) | UNITS |
|----------------------------|---|---|------------------|-----------------|------------------|-------|
| ILOGIC | V _{LOGIC} Supply Current (Write/Read) | V_{LOGIC} = 5.5V, V_{CC} = 5.5V, f _{SCK} = 5MHz (for SPI active read and write) | | | 1.5 | mA |
| | | $V_{LOGIC} = 1.2V, V_{CC} = 1.7V, f_{SCK} = 1MHz$ (for SPI active read and write) | | | 30 | μA |
| Icc | V _{CC} Supply Current (Write/Read) | V _{LOGIC} = 5.5V, V _{CC} = 5.5V | | | 100 | μΑ |
| | | V _{LOGIC} = 1.2V, V _{CC} = 1.7V | | | 10 | μΑ |
| I _{LOGIC} SB | V _{LOGIC} Standby Current | V _{LOGIC} = V _{CC} = 5.5V, SPI interface in standby | | | 2 | μΑ |
| | | V _{LOGIC} = 1.2V, V _{CC} = 1.7V, SPI interface in standby | | | 0.5 | μA |
| I _{CC SB} | V _{CC} Standby Current | V _{LOGIC} = V _{CC} = 5.5V, SPI interface in standby | | | 2 | μA |
| | | V _{LOGIC} = 1.2V, V _{CC} = 1.7V, SPI interface in standby | | | 1.2 | μA |
| I _{LOGIC} SHDN | V _{LOGIC} Shutdown Current | V _{LOGIC} = V _{CC} = 5.5V, SPI interface in standby | | | 2 | μA |
| | | V _{LOGIC} = 1.2V, V _{CC} = 1.7V, SPI interface in standby | | | 0.5 | μA |
| I _{CC SHDN} | V _{CC} Shutdown Current | V _{LOGIC} = V _{CC} = 5.5V, SPI interface in standby | | | 2 | μA |
| | | V _{LOGIC} = 1.2V, V _{CC} = 1.7V, SPI interface in standby | | | 1.2 | μA |
| I _{LkgDig} | Leakage Current, at Pins $\overline{\text{CS}}$, SDO, SDI, SCK | Voltage at pin from GND to V _{LOGIC} | -0.4 | <0.1 | 0.4 | μA |

Operating Specifications V_{CC} = 2.7V to 5.5V, V_{LOGIC} = 1.2V to 5.5V over recommended operating conditions unless otherwise stated. Boldface limits apply over the operating temperature range, -40°C to +125°C. (Continued)

| SYMBOL | PARAMETER | TEST CONDITIONS | MIN (Note 19) | TYP (Note 7) | MAX (Note 19) | UNITS |
|---|--|---|------------------|-----------------|------------------|-------|
| ^t DCP | Wiper Response Time | W option; CS rising edge to wiper new position, from 10% to 90% of final value. | | 0.4 | | μs |
| | | U option; CS rising edge to wiper new position, from 10% to 90% of final value. | | 1.5 | | μs |
| | | T option; CS rising edge to wiper new position, from 10% to 90% of final value. | | 3.5 | | μs |
| tShdnRec | DCP Recall Time from Shutdown Mode | CS rising edge to wiper recalled position and RH connection | | 1.5 | | μs |
| V _{CC,} V _{LOGIC} Ramp | V _{CC} , V _{LOGIC} Ramp Rate (Note 20) | Ramp monotonic at any level | 0.01 | | 50 | V/ms |

Serial Interface Specification For SCK, SDI, SDO, CS Unless Otherwise Noted.

| SYMBOL | PARAMETER | TEST CONDITIONS | MIN (Note 19) | TYP (Note 7) | MAX (Note 19) | UNITS |
|-------------------|--|--|---------------------------|-----------------|--------------------------|-------|
| VIL | Input LOW Voltage | | -0.3 | | 0.3 x V _{LOGIC} | V |
| VIH | Input HIGH Voltage | | 0.7 x V _{LOGIC} | | V _{LOGIC} + 0.3 | v |
| Hysteresis | SDI and SCK Input Buffer | V _{LOGIC} > 2V | 0.05 x V _{LOGIC} | | | v |
| | Hysteresis | V _{LOGIC} < 2V | 0.1 x V _{LOGIC} | | | v |
| V _{OL} | SDO Output Buffer LOW Voltage | I _{OL} = 3mA, V _{LOGIC} > 2V | 0 | | 0.4 | v |
| | | I _{OL} = 1.5mA, V _{LOGIC} < 2V | | | 0.2 x V _{LOGIC} | v |
| R _{pu} | SDO Pull-Up Resistor Off-Chip | Maximum is determined by t_{RO} and t_{FO} with maximum bus load Cb = 30pF, f_{SCK} = 5MHz | | | 1.5 | kΩ |
| C _{pin} | SCK, SDO, SDI, \overline{CS} Pin Capacitance | | | 10 | | pF |
| fsck | SCK Frequency | V _{LOGIC} = 1.7V to 5.5V | | | 5 | MHz |
| | | V _{LOGIC} = 1.2V to 1.6V | | | 1 | MHz |
| tcyc | SPI Clock Cycle Time | V _{LOGIC} ≥ 1.7V | 200 | | | ns |
| t _{WH} | SPI Clock High Time | V _{LOGIC} ≥ 1.7V | 100 | | | ns |
| t _{WL} | SPI Clock Low Time | V _{LOGIC} ≥ 1.7V | 100 | | | ns |
| t _{LEAD} | Lead Time | V _{LOGIC} ≥ 1.7V | 250 | | | ns |
| t _{LAG} | Lag Time | V _{LOGIC} ≥ 1.7V | 250 | | | ns |
| t _{SU} | SDI, SCK and \overline{CS} Input Setup Time | V _{LOGIC} ≥ 1.7V | 50 | | | ns |
| t _H | SDI, SCK and \overline{CS} Input Hold Time | $V_{LOGIC} \ge 1.7V$ | 50 | | | ns |
| t _{RI} | SDI, SCK and \overline{CS} Input Rise Time | V _{LOGIC} ≥ 1.7V | 10 | | | ns |
| t _{FI} | SDI, SCK and CS Input Fall Time | V _{LOGIC} ≥ 1.7V | 10 | | 20 | ns |
| t _{DIS} | SDO Output Disable Time | V _{LOGIC} ≥ 1.7V | 0 | | 100 | ns |
| t _{S0} | SDO Output Setup Time | V _{LOGIC} ≥ 1.7V | 50 | | | ns |
| t _V | SDO Output Valid Time | V _{LOGIC} ≥ 1.7V | 150 | | | ns |
| t _{HO} | SDO Output Hold Time | V _{LOGIC} ≥ 1.7V | 0 | | | ns |

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Serial Interface Specification For SCK, SDI, SDO, CS Unless Otherwise Noted. (Continued)

| SYMBOL | PARAMETER | TEST CONDITIONS | MIN (Note 19) | TYP (Note 7) | MAX (Note 19) | UNITS |
|-----------------|----------------------|-------------------------------------|------------------|-----------------|------------------|-------|
| t _{RO} | SDO Output Rise Time | $R_{pu} = 1.5k$, Cbus = 30pF | | | 60 | ns |
| t _{FO} | SDO Output Fall Time | R _{pu} = 1.5k, Cbus = 30pF | | | 60 | ns |
| t _{CS} | CS Deselect Time | | 2 | | | μs |

NOTES:

7. Typical values are for $T_A = +25$ °C and 3.3V supply voltages.

LSB = [V(RW)₁₂₇ - V(RW)₀]/127. V(RW)₁₂₇ and V(RW)₀ are V(RW) for the DCP register set to 7F hex and 00 hex respectively. LSB is the incremental voltage when changing from one tap to an adjacent tap.

9. ZS error = $V(RW)_0/LSB$.

10. FS error = $[V(RW)_{127} - V_{CC}]/LSB$.

11. DNL = $[V(RW)_i - V(RW)_{i-1}]/LSB-1$, for i = 1 to 127. i is the DCP register setting.

12. INL = $[V(RW)_i - i \cdot LSB - V(RW)_0]/LSB$ for i = 1 to 127

13. $TC_{V} = \frac{Max(V(RW)_{i}) - Min(V(RW)_{i})}{V(RW_{i}(+25^{\circ}C))} \times \frac{10^{6}}{+165^{\circ}C}$ for i = 8 to 127 decimal, T = -40°C to +125°C. Max() is the maximum value of the wiper voltage over the temperature range.

- 14. MI = |RW₁₂₇ RW₀|/127. MI is a minimum increment. RW₁₂₇ and RW₀ are the measured resistances for the DCP register set to 7F hex and 00 hex respectively.
- 15. Roffset = RW_0/MI , when measuring between RW and RL. Roffset = RW_{127}/MI , when measuring between RW and RH.
- 16. RDNL = $(RW_i RW_{i-1})/MI 1$, for i = 8 to 127.
- 17. RINL = $[RW_i (MI \cdot i) RW_0]/MI$, for i = 8 to 127.

 $18. TC_{R} = \frac{[Max(Ri) - Min(Ri)]}{Ri(+25°C)} \times \frac{10^{6}}{+165°C}$ for i = 8 to 127, T = -40°C to +125°C. Max() is the maximum value of the resistance and Min() is the minimum value of the resistance over the temperature range.

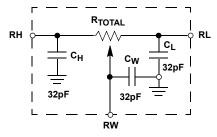
19. Compliance to datasheet limits is assured by one or more methods: production test, characterization and/or design.

20. It is preferable to ramp up both the V_{LOGIC} and the V_{CC} supplies at the same time. If this is not possible it is recommended to ramp-up the V_{LOGIC} first followed by the V_{CC}.

21. VMATCH = [V(RWx)i - V(RWy)i]/LSB, for i = 1 to 127, x = 0 to 1 and y = 0 to 1.

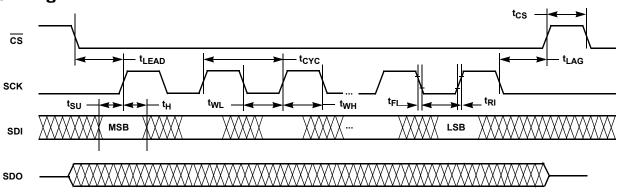
22. RMATCH = (RWi, x - RWi, y)/MI, for i = 1 to 127, x = 0 to 1 and y = 0 to 1.

DCP Macro Model

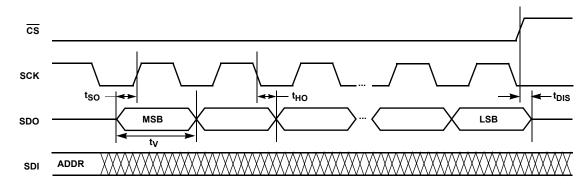


Timing Diagrams

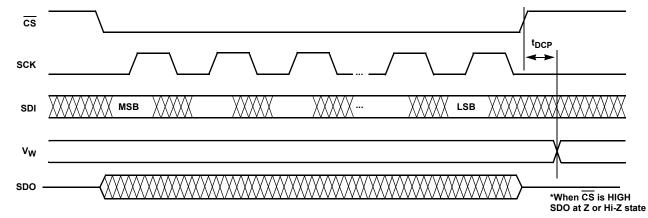


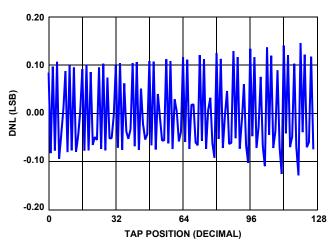


Output Timing



XDCP™ Timing (for All Load Instructions)





Typical Performance Curves



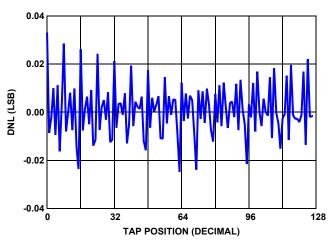


FIGURE 4. 50k Ω DNL vs TAP POSITION, V_{CC} = 3.3V, +25 °C

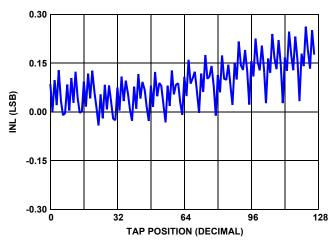


FIGURE 5. 10kΩ INL vs TAP POSITION, V_{CC} = 3.3V, +25°C

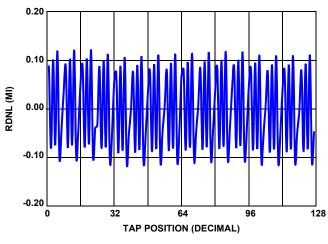
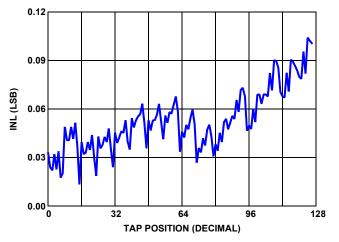


FIGURE 7. 10k Ω RDNL vs TAP POSITION, V_{CC} = 3.3V, +25 °C





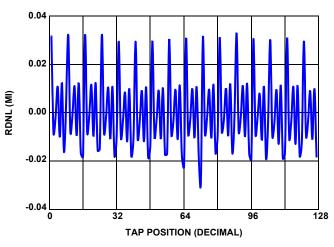


FIGURE 8. 50k Ω RDNL vs TAP POSITION, V_{CC} = 3.3V, +25 °C

Typical Performance Curves (Continued)

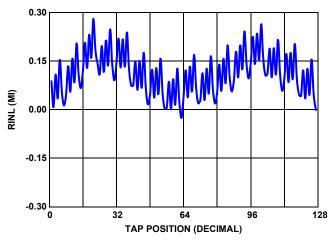


FIGURE 9. 10kQ RINL vs TAP POSITION, VCC = 3.3V, +25°C

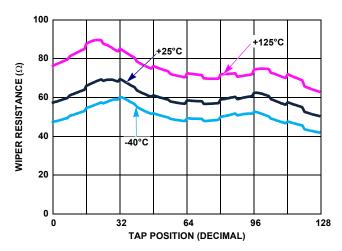


FIGURE 11. 10k Ω WIPER RESISTANCE vs TAP POSITION, V_{CC} = 3.3V

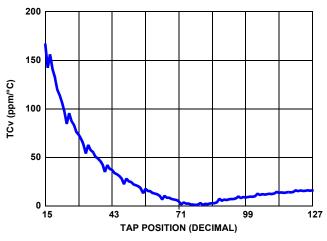


FIGURE 13. 10k Ω TCv vs TAP POSITION, V_CC = 3.3V

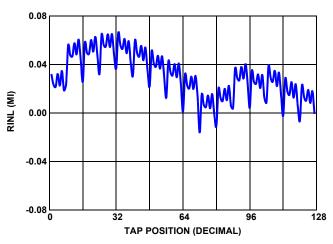


FIGURE 10. 50kQ RINL vs TAP POSITION, V_{CC} = 3.3V, +25°C

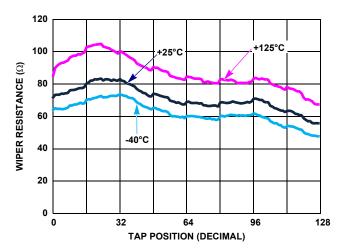


FIGURE 12. 50k Ω WIPER RESISTANCE vs TAP POSITION, V_{CC} = 3.3V

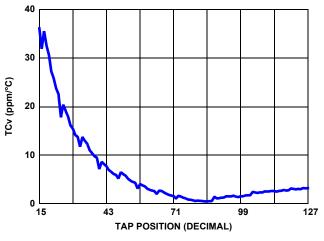
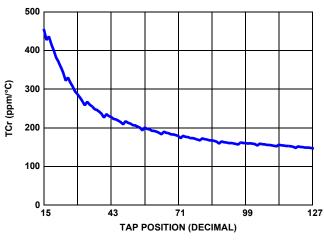


FIGURE 14. 50k Ω TCv vs TAP POSITION, V_{CC} = 3.3V

Typical Performance Curves (Continued)





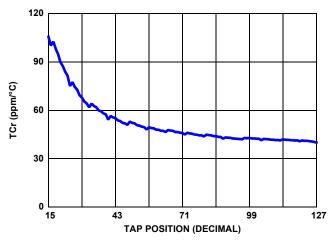


FIGURE 16. 50k Ω TCr vs TAP POSITION, V_{CC} = 3.3V

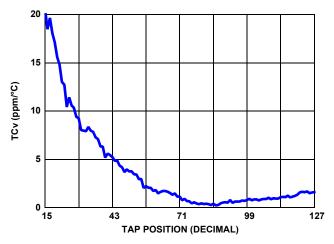


FIGURE 17. 100k Ω TCv vs TAP POSITION, V_CC = 3.3V

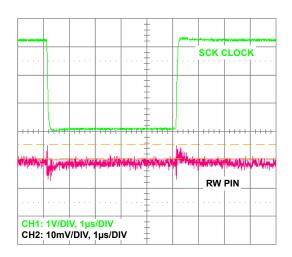


FIGURE 19. WIPER DIGITAL FEED-THROUGH

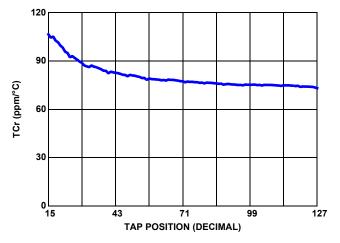


FIGURE 18. 100k Ω TCr vs TAP POSITION, V_{CC} = 3.3V

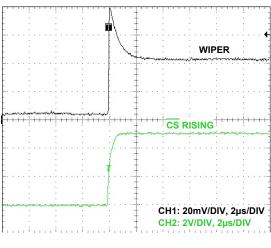


FIGURE 20. WIPER TRANSITION GLITCH

Typical Performance Curves (Continued)

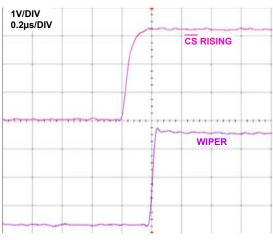


FIGURE 21. WIPER LARGE SIGNAL SETTLING TIME

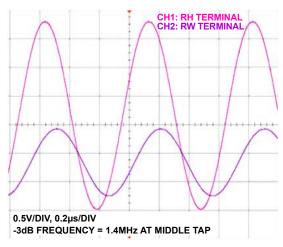


FIGURE 23. 10kΩ -3dB CUT OFF FREQUENCY

Functional Pin Descriptions

Potentiometers Pins

RHI AND RLI

The high (RHi, i = 0, 1) and low (RLi, i = 0, 1) terminals of the ISL23428 are equivalent to the fixed terminals of a mechanical potentiometer. RHi and RLi are referenced to the relative position of the wiper and not the voltage potential on the terminals. With WRi set to 127 decimal, the wiper will be closest to RHi, and with the WRi set to 0, the wiper is closest to RLi.

RWI

RWi (i = 0, 1) is the wiper terminal, and it is equivalent to the movable terminal of a mechanical potentiometer. The position of the wiper within the array is determined by the WRi register.

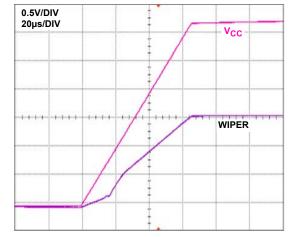


FIGURE 22. POWER-ON START-UP IN VOLTAGE DIVIDER MODE

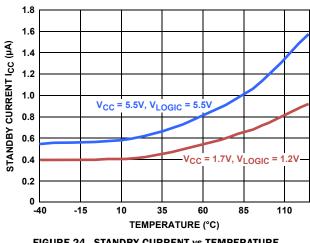


FIGURE 24. STANDBY CURRENT vs TEMPERATURE

Power Pins

V_{CC}

Power terminal for the potentiometer section analog power source. Can be any value needed to support voltage range of DCP pins, from 1.7V to 5.5V, independent of the V_{LOGIC} voltage.

Bus Interface Pins

SERIAL CLOCK (SCK)

This input is the serial clock of the SPI serial interface.

SERIAL DATA INPUT (SDI)

The SDI is a serial data input pin for SPI interface. It receives operation code, wiper address and data from the SPI remote host device. The data bits are shifted in at the rising edge of the serial clock SCK, while the \overline{CS} input is low.

SERIAL DATA OUTPUT (SDO)

The SDO is a serial data output pin. During a read cycle, the data bits are shifted out on the falling edge of the serial clock SCK and will be available to the master on the following rising edge of SCK.

The output type is configured through ACR[1] bit for Push-Pull or Open Drain operation. Default setting for this pin is Push-Pull. An external pull-up resistor is required for Open Drain output operation. When $\overline{\text{CS}}$ is HIGH, the SDO pin is in tri-state (Z) or high-tri-state (Hi-Z) depends on the selected configuration.

CHIP SELECT (\overline{CS})

 $\overline{\text{CS}}$ LOW enables the ISL23428, placing it in the active power mode. A HIGH to LOW transition on $\overline{\text{CS}}$ is required prior to the start of any operation after power-up. When $\overline{\text{CS}}$ is HIGH, the ISL23428 is deselected and the SDO pin is at high impedance, and the device will be in the standby state.

VLOGIC

Digital power source for the logic control section. It supplies an internal level translator for 1.2V to 5.5V serial bus operation. Use the same supply as the l^2C logic source.

Principles of Operation

The ISL23428 is an integrated circuit incorporating two DCPs with its associated registers and an SPI serial interface providing direct communication between a host and the potentiometer. The resistor array is comprised of individual resistors connected in series. At either end of the array and between each resistor is an electronic switch that transfers the potential at that point to the wiper.

The electronic switches on the device operate in a "make-before-break" mode when the wiper changes tap positions.

Voltage at any DCP pins, RHi, RLi or RWi, should not exceed V_{CC} level at any conditions during power-up and normal operation.

The V_{LOGIC} pin is the terminal for the logic control digital power source. It should use the same supply as the SPI logic source which allows reliable communication with a wide range of microcontrollers and is independent from the V_{CC} level. This is extremely important in systems where the master supply has lower levels than DCP analog supply.

DCP Description

Each DCP is implemented with a combination of resistor elements and CMOS switches. The physical ends of each DCP are equivalent to the fixed terminals of a mechanical potentiometer (RHi and RLi pins). The RWi pin of the DCP is connected to intermediate nodes, and is equivalent to the wiper terminal of a mechanical potentiometer. The position of the wiper terminal within the DCP is controlled by an 8-bit volatile Wiper Register (WRi). When the WR of a DCP contains all zeroes (WRi[7:0] = 00h), its wiper terminal (RWi) is closest to its "Low" terminal (RLi). When the WRi register of a DCP contains all ones (WRi[7:0] = 7Fh), its wiper terminal (RWi) is closest to its "High" terminal (RHi). As the value of the WRi increases from all zeroes (0) to all ones (127 decimal), the wiper moves monotonically from the position closest to RLi to the position closest to RHi. At the same time, the resistance between RWi and RLi increases monotonically, while the resistance between RHi and RWi decreases monotonically.

While the ISL23428 is being powered up, both WRi are reset to 40h (64 decimal), which positions RWi at the center between RLi and RHi.

The WRi can be read or written to directly using the SPI serial interface, as described in the following sections.

Memory Description

The ISL23428 contains three volatile 8-bit registers: Wiper Register WR0, Wiper Register WR1, and Access Control Register (ACR). Memory map of ISL23428 is shown in Table 1. The Wiper Register WR0 at address 0 contains current wiper position of DCP0; the Wiper Register WR1 at address 1 contains current wiper position of DCP1. The Access Control Register (ACR) at address 10h contains information and control bits described in Table 2.

| TABLE 1. MEMORY MAR |
|---------------------|
|---------------------|

| ADDRESS (hex) | VOLATILE REGISTER NAME | DEFAULT SETTING (hex) |
|------------------|---------------------------|--------------------------|
| 10 | ACR | 40 |
| 1 | WR1 | 40 |
| 0 | WR0 | 40 |

TABLE 2. ACCESS CONTROL REGISTER (ACR)

| BIT # | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|----------------|---|------|---|---|---|---|-----|---|
| NAME/ Value | 0 | SHDN | 0 | 0 | 0 | 0 | SDO | 0 |

The SDO bit (ACR[1]) configures type of SDO output pin. The default value of SDO bit is 0 for Push-Pull output. The SDO pin can be configured as Open Drain output for some applications. In this case, an external pull-up resistor is required; reference the "Serial Interface Specification" on page 7.

Shutdown Function

The \overline{SHDN} bit (ACR[6]) disables or enables shutdown mode for all DCP channels simultaneously. When this bit is 0, i.e., each DCP is forced to end-to-end open circuit and each RW shorted to RL through a $2k\Omega$ serial resistor, as shown in Figure 25. Default value of the \overline{SHDN} bit is 1.

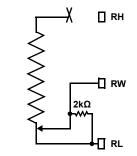


FIGURE 25. DCP CONNECTION IN SHUTDOWN MODE

When the device enters shutdown, all current DCP WR settings are maintained. When the device exits shutdown, the wipers will return to the previous WR settings after a short settling time (see Figure 26).

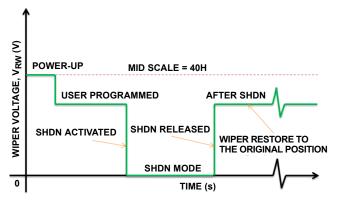


FIGURE 26. SHUTDOWN MODE WIPER RESPONSE

SPI Serial Interface

The ISL23428 supports an SPI serial protocol, mode 0. The device is accessed via the SDI input and SDO output with data clocked in on the rising edge of SCK, and clocked out on the falling edge of SCK. \overline{CS} must be LOW during communication with the ISL23428. The SCK and \overline{CS} lines are controlled by the host or master. The ISL23428 operates only as a slave device.

All communication over the SPI interface is conducted by sending the MSB of each byte of data first.

Protocol Conventions

The SPI protocol contains Instruction Byte followed by one or more Data Bytes. A valid Instruction Byte contains instruction as the three MSBs, with the following five register address bits (see Table 3).

The next byte sent to the ISL23428 is the Data Byte.

| TADIE 2 | INCTRUCTION | BYTE FORMAT |
|----------|-------------|--------------------|
| IADLE J. | INSTRUCTION | BTIE FURMAI |

| BIT # | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | |
|-------|----|----|----|----|----|----|----|----|--|
| | 12 | 11 | 10 | R4 | R3 | R2 | R1 | R0 | |

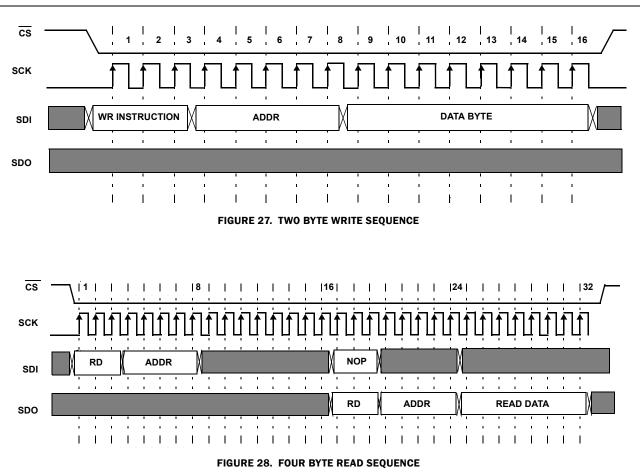
Table 4 contains a valid instruction set for ISL23428.

If the [R4:R0] bits are zero or one, then the read or write is to the WRi register. If the [R4:R0] are 10000, then the operation is to the ACR.

TABLE 4. INSTRUCTION SET

| INSTRUCTION SET | | | | | | | | | | |
|-----------------|----|----|----|----|----|----|----|-----------------|--|--|
| 12 | 11 | 10 | R4 | R3 | R2 | R1 | RO | OPERATION | | |
| 0 | 0 | 0 | х | х | х | x | х | NOP | | |
| 0 | 0 | 1 | х | х | х | x | х | ACR READ | | |
| 0 | 1 | 1 | х | х | х | x | х | ACR WRTE | | |
| 1 | 0 | 0 | R4 | R3 | R2 | R1 | RO | WRi or ACR READ | | |
| 1 | 1 | 0 | R4 | R3 | R2 | R1 | RO | WRi or ACR WRTE | | |

Where X means "do not care".



Write Operation

A write operation to the ISL23428 is a two or more bytes operation. First, It requires the \overline{CS} transition from HIGH-to-LOW. Then the host sends a valid Instruction Byte, followed by one or more Data Bytes to the SDI pin. The host terminates the write operation by pulling the \overline{CS} pin from LOW-to-HIGH. Instruction is executed on the rising edge of \overline{CS} (see Figure 27).

Read Operation

A Read operation to the ISL23428 is a four byte operation. First, It requires the \overline{CS} transition from HIGH-to-LOW. Then the host sends a valid Instruction Byte, followed by a "dummy" Data Byte, NOP Instruction Byte and another "dummy" Data Byte to SDI pin. The SPI host receives the Instruction Byte (instruction code + register address) and requested Data Byte from SDO pin on the rising edge of SCK during third and fourth bytes, respectively. The host terminates the read by pulling the \overline{CS} pin from LOW-to-HIGH (see Figure 28).

Applications Information

Communicating with ISL23428

Communication with ISL23428 proceeds using SPI interface through the ACR (address 10000b), WR0 (addresses 00000b) and WR1 (addresses 00001b) registers.

The wiper of the potentiometer is controlled by the WRi register. Writes and reads can be made directly to these registers to control and monitor the wiper position.

Daisy Chain Configuration

When an application needs more than one ISL23428, it can communicate with all of them without additional \overline{CS} lines by daisy chaining the DCPs as shown in Figure 29. In Daisy Chain configuration, the SDO pin of the previous chip is connected to the SDI pin of the following chip, and each \overline{CS} and SCK pins are connected to the corresponding microcontroller pins in parallel, like regular SPI interface implementation. The Daisy Chain configuration can also be used for simultaneous setting of multiple DCPs.

NOTE: The number of daisy chained DCPs is limited only by the driving capabilities of the SCK and \overline{CS} pins of the microcontroller; for larger number of SPI devices, buffering of SCK and \overline{CS} lines is required.

Daisy Chain Write Operation

The write operation starts by HIGH-to-LOW transition on \overline{CS} line, followed by N number of two bytes write instructions on SDI line with reversed chain access sequence: the instruction byte + data byte for the last DCP in chain is going first, as shown in Figure 30, where N is a number of DCPs in chain. The serial data is going through DCPs from DCP0 to DCP(N-1) as follows: DCP0 -> DCP1 -> DCP2 -> ... -> DCP(N-1). The write instruction is executed on the rising edge of \overline{CS} for all N DCPs simultaneously.

Daisy Chain Read Operation

The read operation consists of two parts: first, send the read instructions (N two bytes operation) with valid address; second, read the requested data while sending NOP instructions (N two bytes operation) as shown in Figures 31 and 32.

The first part starts by HIGH-to-LOW transition on \overline{CS} line, followed by N two bytes read instruction on SDI line with reversed chain access sequence: the instruction byte + dummy data byte for the last DCP in chain is going first, followed by LOW-to-HIGH transition on \overline{CS} line. The read instructions are executed during the second part of read sequence. It also starts by HIGH-to-LOW transition on \overline{CS} line, followed by N number of two bytes NOP instructions on SDI line and LOW-to-HIGH transition of \overline{CS} . The data is read on every even byte during the second part of the read sequence while every odd byte contains code 111b followed by address from which the data is being read.

Wiper Transition

When stepping up through each tap in voltage divider mode, some tap transition points can result in noticeable voltage transients, or overshoot/undershoot, resulting from the sudden transition from a very low impedance "make" to a much higher impedance "break" within a short period of time (<1 μ s). There are several code transitions such as 0Fh to 10h, 1Fh to 20h,..., 6Fh to 7Fh, which have higher transient glitch.

NOTE: That all switching transients will settle well within the settling time as stated in the datasheet. A small capacitor can be added externally to reduce the amplitude of these voltage transients, but that will also reduce the useful bandwidth of the circuit, thus this may not be a good solution for some applications. It may be a good idea, in that case, to use fast amplifiers in a signal chain for fast recovery.

V_{LOGIC} Requirements

It is recommended to keep V_{LOGIC} powered all the time during normal operation. In a case where turning V_{LOGIC} OFF is necessary, it is recommended to ground the V_{LOGIC} pin of the ISL23428. Grounding the V_{LOGIC} pin or both V_{LOGIC} and V_{CC} does not affect other devices on the same bus. It is good practice to put a 1µF capacitor in parallel with 0.1µF decoupling capacitor close to the V_{LOGIC} pin.

V_{CC} Requirements and Placement

It is recommended to put a $1\mu F$ capacitor in parallel with $0.1\mu F$ decoupling capacitor close to the V_{CC} pin.

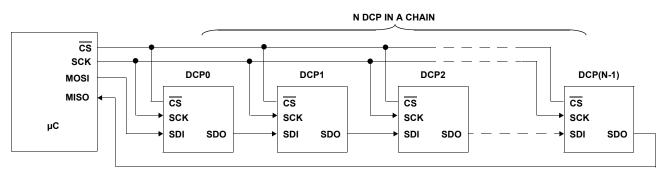
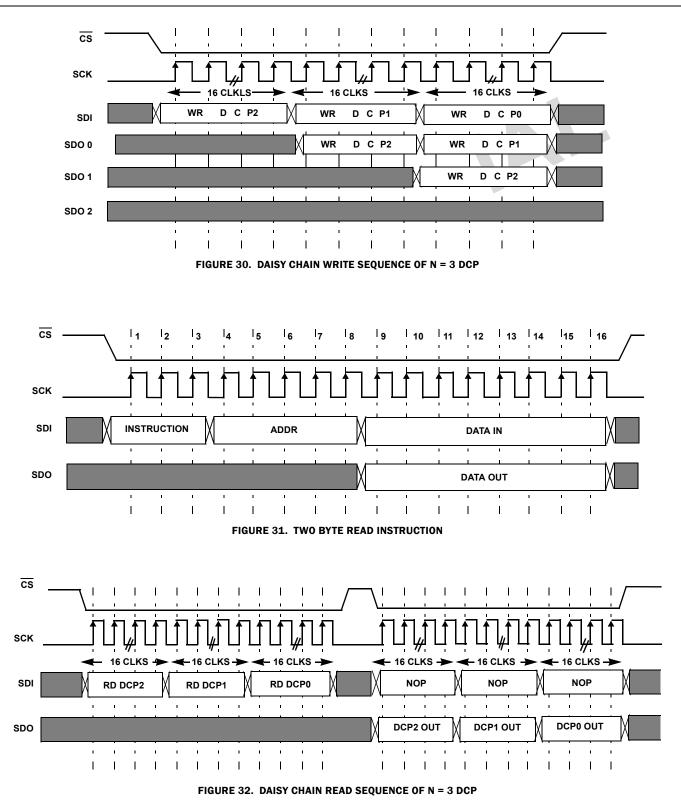


FIGURE 29. DAISY CHAIN CONFIGURATION



Revision History

The revision history provided is for informational purposes only and is believed to be accurate, but not warranted. Please go to web to make sure you have the latest Rev.

| DATE | REVISION | CHANGE |
|---------|----------|--|
| 9/23/15 | FN7904.2 | Updated the Ordering Information table on page 3. Replaced the Products section with the About Intersil section. Updated Package Outline Drawing L16.2.6X1.8A to the latest revision. Changes were as follows: -Changed in Note 5 0.30 to 0.25. |
| 7/9/12 | FN7904.1 | Ordering information table: Three part number listed incorrectly. Changed part number from 23425 to ISL23428. |
| 8/25/11 | FN7904.0 | Initial Release. |

About Intersil

Intersil Corporation is a leading provider of innovative power management and precision analog solutions. The company's products address some of the largest markets within the industrial and infrastructure, mobile computing and high-end consumer markets.

For the most updated datasheet, application notes, related documentation and related parts, please see the respective product information page found at <u>www.intersil.com</u>.

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Reliability reports are also available from our website at <u>www.intersil.com/support</u>.

For additional products, see <u>www.intersil.com/en/products.html</u>

Intersil products are manufactured, assembled and tested utilizing ISO9001 quality systems as noted in the quality certifications found at <u>www.intersil.com/en/support/qualandreliability.html</u>

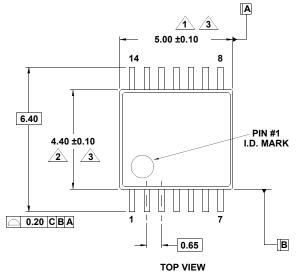
Intersil products are sold by description only. Intersil Corporation reserves the right to make changes in circuit design, software and/or specifications at any time without notice. Accordingly, the reader is cautioned to verify that data sheets are current before placing orders. Information furnished by Intersil is believed to be accurate and reliable. However, no responsibility is assumed by Intersil or its subsidiaries for its use; nor for any infringements of patents or other rights of third parties which may result from its use. No license is granted by implication or otherwise under any patent or patent rights of Intersil or its subsidiaries.

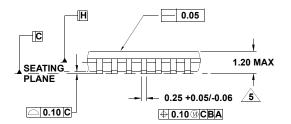
For information regarding Intersil Corporation and its products, see www.intersil.com

Package Outline Drawing

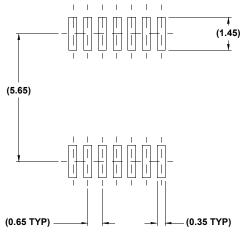
M14.173

14 LEAD THIN SHRINK SMALL OUTLINE PACKAGE (TSSOP) Rev 3, 10/09











NOTES:

- 1. Dimension does not include mold flash, protrusions or gate burrs. Mold flash, protrusions or gate burrs shall not exceed 0.15 per side.
- 2. Dimension does not include interlead flash or protrusion. Interlead flash or protrusion shall not exceed 0.25 per side.
- 3. Dimensions are measured at datum plane H.

SEE DETAIL "X"

0.09-0.20

0.90 +0.15/-0.10

0.05 MIN

0.15 MAX

END VIEW

DETAIL "X"

-1.00 REF-

GAUGE

0°-8°

0.60 ±0.15

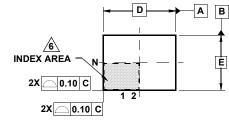
0.25

PLANE

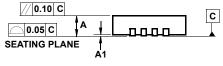
- 4. Dimensioning and tolerancing per ASME Y14.5M-1994.
- 5. Dimension does not include dambar protrusion. Allowable protrusion shall be 0.80mm total in excess of dimension at maximum material condition. Minimum space between protrusion and adjacent lead is 0.07mm.
 6. Dimension in () are for reference only.
- 7. Conforms to JEDEC MO-153, variation AB-1.

ISL23428

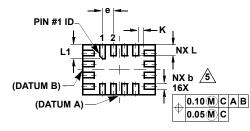
Ultra Thin Quad Flat No-Lead Plastic Package (UTQFN)



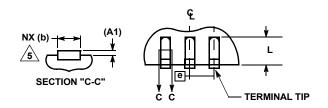


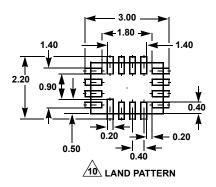






BOTTOM VIEW





L16.2.6x1.8A

16 LEAD ULTRA THIN QUAD FLAT NO-LEAD PLASTIC PACKAGE

| | ľ | | | |
|--------|------|-----------|------|---|
| SYMBOL | MIN | NOTES | | |
| А | 0.45 | 0.50 | 0.55 | - |
| A1 | - | - | 0.05 | - |
| A3 | | 0.127 REF | | - |
| b | 0.15 | 0.20 | 0.25 | 5 |
| D | 2.55 | 2.60 | 2.65 | - |
| E | 1.75 | - | | |
| е | | - | | |
| K | 0.15 | - | - | - |
| L | 0.35 | 0.40 | 0.45 | - |
| L1 | 0.45 | 0.50 | 0.55 | - |
| N | | 2 | | |
| Nd | | 3 | | |
| Ne | | 3 | | |
| θ | 0 | 4 | | |

NOTES:

- 1. Dimensioning and tolerancing conform to ASME Y14.5-1994.
- 2. N is the number of terminals.
- 3. Nd and Ne refer to the number of terminals on D and E side, respectively.
- 4. All dimensions are in millimeters. Angles are in degrees.
- 5. Dimension b applies to the metallized terminal and is measured between 0.15mm and 0.25mm from the terminal tip.
- 6. The configuration of the pin #1 identifier is optional, but must be located within the zone indicated. The pin #1 identifier may be either a mold or mark feature.
- 7. Maximum package warpage is 0.05mm.
- 8. Maximum allowable burrs is 0.076mm in all directions.
- 9. JEDEC Reference MO-255.
- 10. For additional information, to assist with the PCB Land Pattern Design effort, see Intersil Technical Brief TB389.

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ISL23428TFRUZ-T7AISL23428TFRUZ-TKISL23428TFVZISL23428TFVZ-T7AISL23428TFVZ-TKISL23428WFRUZ-T7AISL23428WFRUZ-TKISL23428WFVZISL23428WFVZ-T7AISL23428WFVZ-TK