

#### General Description

The MAX548A/MAX549A/MAX550A serial, 8-bit voltageoutput digital-to-analog converters (DACs) operate from a single +2.5V to +5.5V supply. Their ±1LSB TUE specification is guaranteed over temperature. Operating current (supply current plus reference current) is typically  $75\mu A$  per DAC with  $V_{DD} = 2.5V$ . In shutdown, the DAC is disconnected from the reference, reducing current drain to less than 1µA. The MAX548A/MAX549A allow each DAC to be shut down independently.

The 10MHz, 3-wire serial interface is compatible with SPI™/QSPI™ and Microwire™ interface standards. Double-buffered inputs provide flexibility when updating the DACs; the input and DAC registers can be updated individually or simultaneously.

The MAX548A is a dual DAC with an asynchronous load input; it uses VDD as the reference input. The MAX549A is a dual DAC with an external reference input. The MAX550A is a single DAC with an external reference input and an asynchronous load input.

The MAX548A/MAX549A/MAX550A's low power consumption and small µMAX and DIP packages make these devices ideal for portable and battery-powered applications.

### **Applications**

Battery-Powered Systems VCXO Control Comparator-Level Settings GaAs Amp Bias Control Digital Gain and Offset Control

### **Features**

- ♦ +2.5V to +5.5V Single-Supply Operation
- ♦ ±1LSB (max) TUE
- ♦ Power-On Reset Clears All Registers to Zero
- **♦ Low Operating Current:**  $150\mu A (MAX548A/MAX549A, VREF = +2.5V)$  $75\mu A (MAX550A, V_{REF} = +2.5V)$
- ↑ 1µA Shutdown Mode
- **♦ 10MHz, 3-Wire Serial Interface Compatible with** SPI/QSPI and Microwire
- ♦ µMAX Package—50% Smaller than 8-Pin SO
- **♦ Independent Shutdown of DACs** (MAX548A/MAX549A)

#### Ordering Information

PART	TEMP. RANGE	PIN-PACKAGE†
MAX548ACPA	0°C to +70°C	8 Plastic DIP
MAX548ACUA	0°C to +70°C	8 μMAX
MAX548AC/D	0°C to +70°C	Dice*
MAX548AEPA	-40°C to +85°C	8 Plastic DIP
MAX548AEUA	-40°C to +85°C	8 μMAX

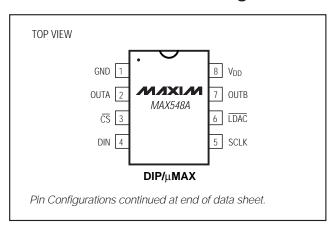
#### Ordering Information continued at end of data sheet.

#### **Selector Guide**

FEATURE	MAX548A	MAX549A	MAX550A
Number of DACs	2	2	1
DAC Reference	V <sub>DD</sub>	External	External
Asynchronous Load DAC Input	V	_	V
μMAX Package	√	√	√

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### Pin Configurations



Maxim Integrated Products 1

<sup>\*</sup>Dice are specified at  $T_A = +25$ °C, DC parameters only. †Contact factory for availability of 8-pin SO package.

#### **ABSOLUTE MAXIMUM RATINGS**

V <sub>DD</sub> , SCLK, DIN, <del>CS</del> , <del>LDAC</del> , OUT_ to GND0.3V to 6V	QO
REF to GND0.3V to (V <sub>DD</sub> + 0.3V)	N
Maximum Current (any pin)±50mA	N
Continuous Power Dissipation (T <sub>A</sub> = +70°C)	Sto
Plastic DIP (derate 9.09mW/°C above +70°C)727mW	Lea
μMAX (derate 4.10mW/°C above +70°C)330mW	

Operating Temperature Ranges	
MAX5AC_ A	0°C to +70°C
MAX5AE_ A	40°C to +85°C
Storage Temperature Range	65°C to +150°C
Lead Temperature (soldering, 10sec)	+300°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

#### **ELECTRICAL CHARACTERISTICS**

 $(V_{DD} = +2.5V \text{ to } +5.5V, T_A = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted. Typical values are at } T_A = +25^{\circ}C.)$ 

PARAMETER	SYMBOL		CONDITIONS	MIN	TYP	MAX	UNITS	
STATIC PERFORMANCE		•						
Resolution	N			8			Bits	
Differential Menlinearity	DNI	Guaranteed	MAX5AEUA (Note 1)			±0.9	LSB	
Differential Nonlinearity	DINL	monotonic	All others			±0.9	LSD	
Total Unadjusted Error	TUE		MAX5AEUA (Note 1)			±1	LSB	
Total Offaujusteu Effor	TUE		All others			±1	LJD	
Zero-Code Error	ZCE					±1	LSB	
Full-Scale Error	FSE					±1	LSB	
REFERENCE INPUT				•				
Reference Input Voltage Range	V <sub>REF</sub>	MAX549A/MA) performance	(550A for specified	2.5		$V_{\mathrm{DD}}$	V	
Reference Input Resistance	Б	MAX549A			16.7		l.O	
DAC Code = 55 Hex (Note 2)	R <sub>REF</sub>	MAX550A			33.3		kΩ	
		MAX549A	VDD = VREF = 5.5V		330	550		
Reference Input Current	IRFF	IVIAAS49A	$V_{DD} = V_{REF} = 2.5V$		150	250		
DAC Code = 55 Hex (Note 3)	IREF	$V_{DD} = V_{REF} = 5.5V$			165	275	μΑ	
		IVIAXSSOA	V <sub>DD</sub> = V <sub>REF</sub> = 2.5V		75	125		
DAC OUTPUT								
DAC Output Voltage Swing		MAX548A		0		$V_{DD}$	V	
DAC Output voltage Swing		MAX549A/MA	(550A	0		VREF	V	
DAC Output Resistance	Rout				33.3		kΩ	
DAC Output Resistance Matching	∆R <sub>OUT</sub> / Rout	MAX548A/MA	MAX548A/MAX549A		±0.2		%	
DIGITAL INPUTS								
Input High Voltage	VIH			0.7V <sub>DD</sub>			V	
Input Low Voltage	VIL					0.3V <sub>DD</sub>	V	
Input Current	liN	VIN = 0V or VD	D			±1	μΑ	
Input Capacitance (Note 4)	CIN					10	рF	

### **ELECTRICAL CHARACTERISTICS (continued)**

(V<sub>DD</sub> = +2.5V to +5.5V, T<sub>A</sub> = T<sub>MIN</sub> to T<sub>MAX</sub>, unless otherwise noted. Typical values are at T<sub>A</sub> = +25°C)

PARAMETER	SYMBOL	CONE	DITIONS	MIN	TYP	MAX	UNITS	
DYNAMIC PERFORMANCE	•	1						
Digital Feedthrough and Crosstalk		CS = high, all digital in	nputs from OV to V <sub>DD</sub>		50		nV-sec	
Voltage-Output Settling Time		To ±1/2LSB, CL = 20p	F		4		μs	
Voltage-Output Slew Rate		C. 20pE	V <sub>DD</sub> = 2.5V		1.4		\//uc	
Voltage-Output Siew Rate		$C_L = 20pF$ $V_{DD} = 5.5V$		3.1			- V/µs	
Wake-Up Time at Power-Up		C <sub>L</sub> = 20pF	•		4		μs	
POWER SUPPLIES	•			•				
Supply Voltage Range	V <sub>DD</sub>	Outputs unloaded, all	inputs = GND or V <sub>DD</sub>	2.5		5.5	V	
Supply Current (MAX548A)	lpp	Outputs unloaded, all inputs = GND or	V <sub>DD</sub> = 5.5V		330	550	μΑ	
Supply Current (MAXS40A)	טטי	V <sub>DD</sub> (Note 5)	$V_{DD} = 2.5V$		150	250	μΛ	
Supply Current (MAX549A/MAX550A)	I <sub>DD</sub>	Outputs unloaded, all VDD = 5.5V	inputs = GND or $V_{DD}$ ;		0.3	10	μA	
Shutdown Current		Shutdown mode		0.3		μΑ		

#### TIMING CHARACTERISTICS

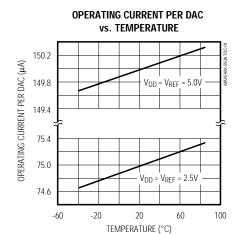
 $(V_{DD} = +2.5V \text{ to } +5.5V, T_A = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted.}$  Digital inputs switching from 0V to  $V_{DD}$ .) (Figure 3) (Note 4)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
SCLK Pulse Width High	tсн		40			ns
SCLK Pulse Width Low	t <sub>CL</sub>		40			ns
DIN to SCLK High Setup	t <sub>DS</sub>		30			ns
DIN to SCLK High Hold	tou	V <sub>DD</sub> = 2.5V	0			nc
DIN to SCEN HIGH HOID	tDH	V <sub>DD</sub> = 5.5V	10			ns
CS Low to SCLK High Setup	tcsso		30			ns
CS High to SCLK High Setup	tcss1		30			ns
SCLK High to CS Low Hold	tCSH0		10			ns
Delay, SCLK High to CS High	tocus	V <sub>DD</sub> = 2.5V	10			nc
Delay, SCLK High to C5 High	tCSH1	V <sub>DD</sub> = 5.5V	20		ns	
CS Pulse Width High	tcsw		40			ns
SCLK Period	tcp		80			ns
LDAC Pulse Width Low	tLDAC	MAX548A/MAX550A only	50			ns
CS High to LDAC Low	tcsld	MAX548A/MAX550A only	50			ns
V <sub>DD</sub> High to <del>CS</del> Low			5			μs

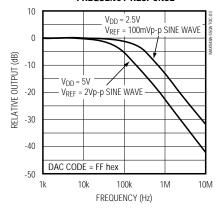
- Note 1: Cold temperature specifications (to -40°C) guaranteed by design using six sigma design limits.
- Note 2: Worst-case input resistance at REF occurs at DAC code 55 hex.
- Note 3: Worst-case reference input current occurs at DAC code 55 hex.
- Note 4: Guaranteed by design. Not production tested.
- Note 5: I<sub>DD</sub> measured with DACs loaded with worst-case DAC code 55 hex.

Typical Operating Characteristics

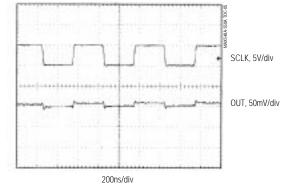
 $(V_{DD} = V_{REF} = 2.5V, R_L = 1M\Omega, C_L = 15pF, T_A = +25^{\circ}C, unless otherwise noted.)$ 



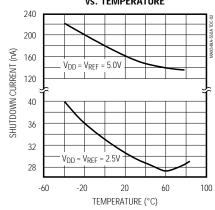
#### MAX549A/MAX550A REFERENCE SMALL-SIGNAL FREQUENCY RESPONSE



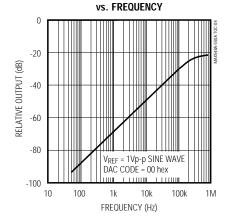
#### DIGITAL FEEDTHROUGH



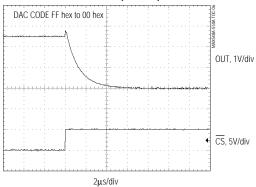
## SHUTDOWN CURRENT vs. Temperature



#### MAX549A/MAX550A REFERENCE AC FEEDTHROUGH

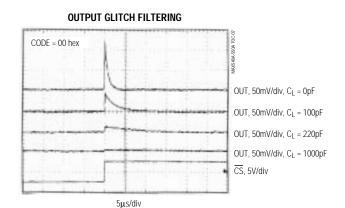


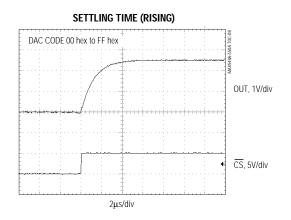
#### SETTLING TIME (FALLING)



### \_Typical Operating Characteristics (continued)

 $(V_{DD} = V_{REF} = 2.5V, R_L = 1M\Omega, C_L = 15pF, T_A = +25^{\circ}C, unless otherwise noted.)$ 





### Pin Description

	PIN		NAME	FUNCTION
MAX548A	MAX549A	MAX550A	NAME	FUNCTION
1	1	1	GND	Ground
2	2	_	OUTA	DAC A Output Voltage
_	_	2	OUT	DAC Output Voltage
3	3	3	<del>CS</del>	Chip-Select Input. A logic low on $\overline{\text{CS}}$ enables serial data to be clocked into the input shift register. Programming commands are executed at $\overline{\text{CS}}$ 's rising edge.
4	4	4	DIN	Serial-Data Input. Data is clocked into the 16-bit input shift register on SCLK's rising edge.
5	5	5	SCLK	Serial-Clock Input. Data is clocked in on SCLK's rising edge.
6	_	6	LDAC	Load DAC Input. After $\overline{\text{CS}}$ goes high and if programmed by the control word, a falling edge on $\overline{\text{LDAC}}$ updates the DAC latch(es). Connect $\overline{\text{LDAC}}$ to $\overline{\text{VDD}}$ if unused.
7	6	_	OUTB	DAC B Output Voltage
_	7	7	REF	External Reference Voltage Input for DAC(s)
8	8	8	V <sub>DD</sub>	Positive Power Supply (+2.5V to +5.5V)

### \_Detailed Description

#### Analog Section

The MAX548A/MAX549A/MAX550A are 8-bit, voltageoutput digital-to-analog converters (DACs). The MAX548A/MAX549A are dual DACs, and the MAX550A is a single DAC. Each DAC consists of an R-2R ladder network that converts 8-bit digital inputs into equivalent analog output voltages in proportion to the applied reference voltage (Figure 1).

The DACs feature double-buffered inputs and unbuffered outputs. The MAX549A/MAX550A require an external reference. The MAX548A's reference inputs are internally connected to V<sub>DD</sub>. The power-supply range is from +2.5V to +5.5V.

#### Reference Input

The voltage applied at REF (VDD for the MAX548A) sets the full-scale output for all the DACs and may range from +2.5V to VDD. The REF input resistance is code dependent, with the lowest value occurring with code 01010101 (55 hex). To minimize INL errors, the reference voltage source should have less than  $3\Omega$  output impedance.

#### **DAC Output**

The MAX548A/MAX549A/MAX550A contain DACs with unbuffered outputs; each output connects directly to an R-2R ladder. Typical output impedance is  $33.3k\Omega$ . This configuration minimizes power consumption and reduces offset errors. For highest accuracy, apply high resistive loads ( $1M\Omega$  and up). Lower resistive loads can be driven, but output loading increases full-scale error.

The magnitude of the expected error is the ratio of the DAC output resistance to the DC load resistance at the output.

Typically, an energy pulse is coupled into the DAC output on CS's rising edge. Since each DAC output is unbuffered, connecting a small capacitor (200pF to 1000pF) from the output to ground creates a lowpass filter that effectively suppresses the pulse for sensitive applications (see *Typical Operating Characteristics*).

#### Shutdown Mode

When the MAX548A/MAX549A/MAX550A are in shutdown mode, the R-2R ladder disconnects from the reference source. The MAX549A/MAX550A supply current does not change, but the REF input current decreases to less than 1 $\mu$ A. This allows the externally applied system reference to remain active with minimal power consumption. The MAX548A supply current also decreases to less than 1 $\mu$ A in shutdown mode. When the MAX548A/MAX549A/MAX550A exit shutdown mode, recovery time is equivalent to the DAC's settling time.

#### Serial Interface

The serial interface is SPI/QSPI and Microwire compatible. An active-low chip select  $\overline{(CS)}$  enables the input shift register to receive data from the serial input (DIN). Data is clocked into the shift register on the rising edge of the serial-clock signal (SCLK). The clock frequency can be as high as 10MHz.

Transmit data MSB first in one 16-bit word or two 8-bit bytes. The write cycle can be segmented to allow two 8-bit-wide transfers when CS remains low. After all 16 bits are clocked into the input shift register, a rising

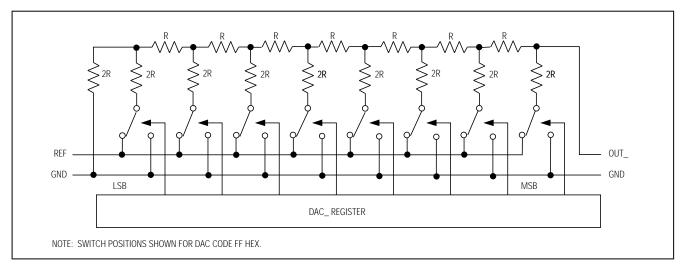


Figure 1. DAC Simplified Circuit Diagram

edge on  $\overline{\text{CS}}$  programs the DAC. The input registers can be loaded independently or simultaneously without updating the DAC registers. This allows both DAC registers to be updated simultaneously with different digital values. The DAC outputs reflect the data stored in the DAC registers. LDAC can be used to asynchronously update the DAC registers independently of  $\overline{\text{CS}}$  (MAX548A/MAX550A). With C1 set high, setting C0 in the control word forces the DAC register(s) to be updated on  $\overline{\text{LDAC}}$ 's falling edge, rather than  $\overline{\text{CS}}$ 's rising edge (Table 1).

#### Initialization

The MAX548A/MAX549A/MAX550A have an internal power-on reset. At power-up, all internal registers are reset to zero; therefore, an initialization write sequence is not necessary.

#### Serial-Input Data Format and Control Codes

The control byte determines which input registers/DAC registers are updated (Table 1). The DAC input registers are updated on the rising edge of  $\overline{CS}$ . The DAC registers can be updated on  $\overline{CS}$ 's rising edge or on  $\overline{LDAC}$ 's falling edge after  $\overline{CS}$  goes high. Bit C0 of the control byte determines how the DAC registers are updated for the MAX548A/MAX550A. The MAX549A has no  $\overline{LDAC}$  pin; the DAC registers are always updated on  $\overline{CS}$ 's rising edge (C0 in the control byte has no effect).

Tables 2, 3, and 4 list the serial-input command format for the MAX548A, MAX549A, and MAX550A, respectively. The 16-bit input word consists of an 8-bit control byte and an 8-bit data byte. The control byte is not decoded internally. Every control bit performs one

Table 1. Control-Byte/Input-Word Bit Definitions

	BIT NAME	STATE	OPERATION					
	UB1*	Х	Unassigned Bit 1					
	UB2	Х	Unassigned Bit 2					
	UB3	Х	Unassigned Bit 3					
	C2	0	Power-Up Mode					
	C2	1	Power-Down Mode					
	C1	0	DAC Register Load Operation Disabled					
CONTROL BYTE	C1	1	DAC Register Load Operation Enabled					
	C0	0	DAC Register Updated on CS's Rising Edge					
	C0	1	DAC Register Updated on LDAC's Falling Edge (MAX549A = Don't Care)					
	A1	0	Do Not Address DAC B (MAX550A = Don't Care)					
	A1	1	Address DAC B (MAX550A = Don't Care)					
	A0	0	Do Not Address DAC A					
	A0	1	Address DAC A					
	D7	_	DAC Data Bit 7 (MSB)					
	D6	_	DAC Data Bit 6					
	D5	_	DAC Data Bit 5					
DATA	D4	_	DAC Data Bit 4					
BYTE	D3	_	DAC Data Bit 3					
	D2	_	DAC Data Bit 2					
	D1		DAC Data Bit 1					
	D0**	_	DAC Data Bit 0 (LSB)					

X = Don't care \*Clocked in first \*\*Clocked in last



function. Data is clocked in starting with unassigned bit 1 (UB1), followed by the remaining control bits and the DAC data byte. The data byte's LSB (D0) is the last bit clocked into the input register (Figure 2).

Table 5 is an example of a 16-bit input word that performs the following functions:

- Loads 80 hex (128 decimal) into the DAC input register (DAC A for the MAX548A/MAX549A)
- Updates the DAC register(s) on  $\overline{CS}$ 's rising edge.

Table 6 shows how to calculate the output voltage based on the input code. Figure 3 gives detailed timing information.

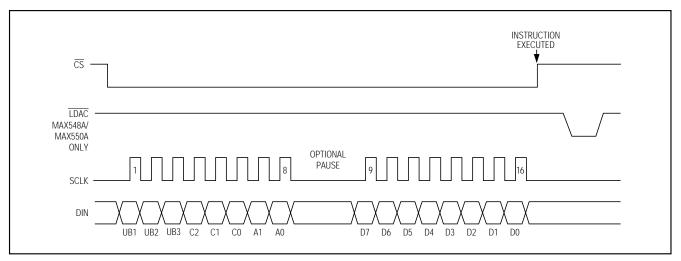


Figure 2. Serial-Interface Timing Diagram

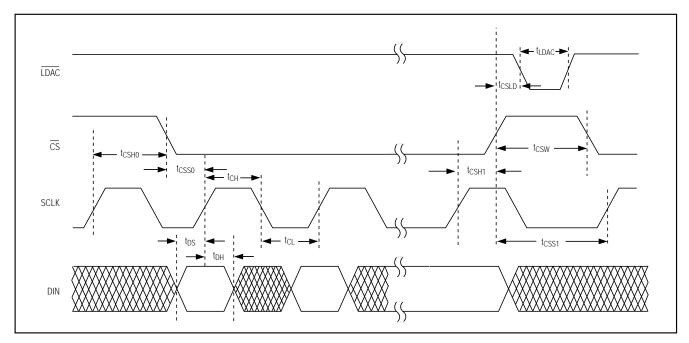


Figure 3. Detailed Serial-Interface Timing Diagram

Table 2. MAX548A Serial-Interface Programming Commands

		CON	TROL	BYTE	<u> </u>			DATA BYTE LDAC		
		Loa	aded F	First				Loaded Last	LDAC	COMMAND (Commands executed on CS's rising edge)
UB1	UB2	UB3	C2	C1	C0	A1	A0	D7D0	Pin 6	(commands excedited on ce a name eage)
UNA	SSIGNE	D COM	IMAN	DS						
Χ	Χ	Х	0	0	Х	0	0	XXXXXXX	X	Unassigned command
X	Х	Х	1	Х	X	0	0	XXXXXXX	X	Unassigned operation
COM	MANDS	LOAD	ING II	NPUT	REGI	STEF	R(S) O	NLY		
Х	Х	Х	0	0	Х	0	1	8-Bit DAC Data	X	Load DAC A input register. DAC B input register and both DAC registers unchanged.
Х	Х	Х	0	0	Х	1	0	8-Bit DAC Data	Х	Load DAC B input register. DAC A input register and both DAC registers unchanged.
Х	Х	Х	0	0	Х	1	1	8-Bit DAC Data	Х	Load both DAC input registers. Both DAC registers unchanged.
COM	MANDS	UPDA	TING	DAC	REGI	STER	(S)		'	
Х	Х	Х	0	1	0	0	0	XXXXXXX	Х	Update both DAC registers with current contents of their input registers. Both input registers unchanged.
Х	Х	Х	0	1	0	0	1	8-Bit DAC Data	Х	Load DAC A input register and update both DAC registers. DAC B input register unchanged.
Х	Х	Х	0	1	0	1	0	8-Bit DAC Data	Х	Load DAC B input register and update both DAC registers. DAC A input register unchanged.
Х	Х	Х	0	1	0	1	1	8-Bit DAC Data	Х	Load both DAC input registers and update both DAC registers.
Х	Х	Х	0	1	1	0	0	XXXXXXXX	0	Update both DAC registers with current contents of their input registers. Both input registers unchanged.
Х	Х	Х	0	1	1	0	1	8-Bit DAC Data	0	Load DAC A input register and update both DAC registers. DAC B input register unchanged.
Х	Х	Х	0	1	1	1	0	8-Bit DAC Data	0	Load DAC B input register and update both DAC registers. DAC A input register unchanged.
Х	Х	Х	0	1	1	1	1	8-Bit DAC Data	0	Load both DAC input registers and update both DAC registers.
COM	MANDS	UTILIZ	ZING	THE A	SYNO	CHRO	NOUS	S LOAD FUNCTIO	N	
Х	Х	Х	0	1	1	0	0	xxxxxxx	1	After CS's rising edge and on LDAC's falling edge, update both DAC registers with current contents of their input registers. Both input registers unchanged.
Х	Х	Х	0	1	1	0	1	8-Bit DAC Data	1	Load DAC A input register. After CS's rising edge and on LDAC's falling edge, update both DAC registers.
X	Х	Х	0	1	1	1	0	8-Bit DAC Data	1	Load DAC B input register. After CS's rising edge and on LDAC's falling edge, update both DAC registers.
X	Х	Х	0	1	1	1	1	8-Bit DAC Data	1	Load both DAC input registers. After $\overline{\text{CS}}$ 's rising edge and on $\overline{\text{LDAC}}$ 's falling edge, update both DAC registers.

Table 2. MAX548A Serial-Interface Programming Commands (continued) COMMANDS FOR POWERING DOWN

		CON	ΓROL	BYTE	<b>=</b>			DATA BYTE		
		Loa	aded I	First				Loaded Last	LDAC	COMMAND (Commands executed on CS's rising edge)
UB1	UB2	UB3	C2	C1	C0	A1	A0	D7D0 Pin 6		(Commands executed on C5's rising edge)
COMI	MANDS	POWE	RING	DOW	N ANI	D LOA	DING	INPUT REGISTE	R(S) ONL	Y
Х	Х	Х	1	0	Х	0	1	8-Bit DAC Data	Х	Load DAC A input register and power down DAC A. DAC B registers unchanged.
Χ	Х	Х	1	0	Х	1	0	8-Bit DAC Data	Х	Load DAC B input register and power down DAC B. DAC A registers unchanged.
Х	Х	Х	1	0	Х	1	1	8-Bit DAC Data	Х	Load both DAC input registers and power down both DACs. Both DAC registers unchanged
COMI	MANDS	POWE	RING	DOW	N ANI	D UPE	ATIN	G DAC REGISTEI	R(S)	
Χ	Х	Х	1	1	0	0	1	8-Bit DAC Data	X	Load DAC A input register, power down DAC A, and update both DAC registers. DAC B input register unchanged.
Х	Х	Х	1	1	0	1	0	8-Bit DAC Data	Х	Load DAC B input register, power down DAC B, and update both DAC registers. DAC A input register unchanged.
Х	Х	Х	1	1	0	1	1	8-Bit DAC Data	Х	Load both DAC input registers, power down both DACs, and update both DAC registers.
Х	Х	Х	1	1	1	0	1	8-Bit DAC Data	0	Load DAC A input register, power down DAC A, and update both DAC registers. DAC B input register unchanged.
Х	Х	Х	1	1	1	1	0	8-Bit DAC Data	0	Load DAC B input register, power down DAC B, and update both DAC registers. DAC A input register unchanged.
Х	Х	Х	1	1	1	1	1	8-Bit DAC Data	0	Load both DAC input registers and power down both DACs. Update both DAC registers.
COMI	MANDS	POWE	RING	DOW	N ANI	UTI	LIZIN	THE ASYNCHR	ONOUS L	OAD FUNCTION
Х	X	X	1	1	1	0	1	8-Bit DAC Data	1	Load DAC A input register and power down DAC A. While powered down, on LDAC's falling edge, update both DAC registers. DAC B input register unchanged.
Х	Х	Х	1	1	1	1	0	8-Bit DAC Data	1	Load DAC B input register and power down DAC B. While powered down, on LDAC's falling edge, update both DAC registers. DAC A input register unchanged.
X	Х	Х	1	1	1	1	1	8-Bit DAC Data	1	Load both DAC input registers and power down both DACs. While powered down, on LDAC's falling edge, update both DAC registers.

X = Don't care

Table 3. MAX549A Serial-Interface Programming Commands

CONTROL BYTE					<b>.</b>			DATA BYTE	COMMAND
		Loa	aded F	First				Loaded Last	(Commands executed on CS's rising edge)
UB1	UB2	UB3	C2	C1	C0	A1	A0	D7D0	
UNA	SSIGNE	D COM	IMAN	D					
Х	Х	Х	Χ	0	Х	0	0	XXXXXXXX	Unassigned command
COM	MANDS	LOAD	ING I	NPUT	REG	STEF	(S) O	NLY	
Х	Х	Х	0	0	Х	0	1	8-Bit DAC Data	Load DAC A input register. DAC registers unchanged.
Х	Х	Χ	0	0	Х	1	0	8-Bit DAC Data	Load DAC B input register. DAC registers unchanged.
Х	Х	Х	0	0	Х	1	1	8-Bit DAC Data	Load both DAC input registers. DAC registers unchanged.
COM	MANDS	UPDA	TING	DAC	REGI	STER	(S)		
Х	Х	Х	Х	1	Х	0	0	XXXXXXX	Update both DAC registers with current contents of their input registers. Both input registers unchanged.
Х	Х	Х	0	1	Х	0	1	8-Bit DAC Data	Load DAC A input register and update both DAC registers. DAC B input register unchanged.
Х	Х	Х	0	1	Х	1	0	8-Bit DAC Data	Load DAC B input register and update both DAC registers. DAC A input register unchanged.
Х	Х	Х	0	1	Х	1	1	8-Bit DAC Data	Load both DAC input registers and update both DAC registers.
COM	MANDS	POWE	RING	DOV	VN AN	ID LO	ADIN	G INPUT REGISTE	R(S) ONLY
Х	Х	Х	1	0	Х	0	1	8-Bit DAC Data	Load DAC A input register and power down DAC A. DAC B input register and both DAC registers unchanged.
Х	Х	Х	1	0	Х	1	0	8-Bit DAC Data	Load DAC B input register and power down DAC B. DAC A input register and both DAC registers unchanged.
Х	Х	Х	1	0	Х	1	1	8-Bit DAC Data	Load both DAC input registers and power down both DACs. Both DAC registers unchanged.
COM	MANDS	POWE	RING	DOV	VN AN	ID UP	DATI	NG DAC REGISTER	R(S)
X	X	Х	1	1	Х	0	1	8-Bit DAC Data	Load DAC A input register, power down DAC A, and update both DAC registers. DAC B input register unchanged.
Х	Х	Х	1	1	Х	1	0	8-Bit DAC Data	Load DAC B input register, power down DAC B, and update both DAC registers. DAC A input register unchanged.
Х	Х	Х	1	1	Х	1	1	8-Bit DAC Data	Load both DAC input registers, power down both DACs, and update both DAC registers.

X = Don't care

Table 4. MAX550A Serial-Interface Programming Commands

		CON	TR∩I	RYTE				DATA BYTE					
CONTROL BYTE  Loaded First								Loaded Last	LDAC	COMMAND (Commands executed on CS's rising edge)			
UB1 UB2 UB3 C2 C1 C0 A1 A0				Ι 40	D7D0	Pin 6							
		SIGNED COMMANDS						טטטט	PIN 6				
X	X	X			V			XXXXXXXX		Lineariemed commond			
	1		0	0	X	X	0		X	Unassigned command			
X	X X 1 X X X X 0 XXXXXXXX DOMMANDS LOADING INPUT REGISTER ONLY						Х	Unassigned operation					
						_	_		1				
Χ	X	X	0	0	Χ	Х	1	8-Bit DAC Data	Х	Load DAC input register. DAC register unchanged.			
CON	MANDS	SLOAD	ING E	AC R	EGIS	TER							
Χ	Х	X	0	1	0	Х	0	xxxxxxx	Х	Update DAC register with current contents of input register. Input register unchanged.			
Χ	Х	Х	0	1	0	Х	1	8-Bit DAC Data	Х	Load DAC input register and update DAC register.			
Х	Х	Х	0	1	1	Х	0	xxxxxxx	0	Update DAC register with current contents of input register. Input register unchanged.			
Χ	Х	Х	0	1	1	Х	1	8-Bit DAC Data	0	Load DAC input register and update DAC register.			
CON	COMMANDS UTILIZING THE ASYNCHRONOUS LOAD FUNCTION												
Χ	Х	Х	0	1	1	Х	0	XXXXXXXX	1	After CS's rising edge and on LDAC's falling edge, update DAC register with current contents of input register. Input register unchanged.			
Χ	Х	Х	0	1	1	Х	1	8-Bit DAC Data	1	Load DAC input register. After $\overline{\text{CS}}$ 's rising edge and on LDAC's falling edge, update DAC register.			
CON	MAND	POWER	RING	DOWI	AND	LOA	DING	INPUT REGISTER	RONLY				
Χ	Х	Х	1	0	Χ	Χ	1	8-Bit DAC Data	Х	Load DAC input register and power down DAC.			
CON	MANDS	POWE	RING	DOV	VN AN	ID UP	DATI	NG DAC REGISTE	R	· · · · · · · · · · · · · · · · · · ·			
Χ	X	Х	1	1	0	Х	1	8-Bit DAC Data	Х	Load DAC input register, power down DAC, and update DAC register.			
Χ	Х	Х	1	1	1	Х	1	8-Bit DAC Data	0	Load DAC input register, power down DAC, and update DAC register.			
COMMAND POWERING DOWN AND UTILIZING THE ASYNCHRONOUS LOAD FUNCTION													
Х	X	Х	1	1	1	Х	1	8-Bit DAC Data	1	Load DAC input register and power down DAC. While powered down, on LDAC's falling edge, update DAC register.			

X = Don't care

Table 5. Example Input Word

		•	•												
CONTROL BYTE									DATA BYTE						
Loaded First									Loaded Last						
UB1	UB2	UB3	C2	C1	C0	A1	A0	D7	D6	D5	D4	D3	D2	D1	D0
Х	Х	Х	0	1	0	0	1	1	0	0	0	0	0	0	0

X = Don't care

#### Microprocessor Interfacing

The MAX548A/MAX549A/MAX550A serial interface is SPI/QSPI and Microwire compatible. For SPI/QSPI, clear the CPOL and CPHA bits (CPOL = 0 and CPHA = 0). CPOL = 0 sets the clock idle state to zero, and CPHA = 0 changes data at SCLK's falling edge. This is the Microwire default condition. If a serial port is not available on your microprocessor, three bits of a parallel port can be used to emulate a serial port by bit manipulation. Operate the serial clock only when necessary, to minimize digital feedthrough at the DAC registers.

#### \_Applications Information

### Power-Supply and Ground Considerations

Connect GND to the highest quality ground available. Bypass  $V_{DD}$  with a  $0.1\mu F$  to  $0.22\mu F$  capacitor to GND. The reference input can be used without bypassing. However, for optimum line/load-transient response and noise performance, bypass the reference input with a  $0.1\mu F$  to  $4.7\mu F$  capacitor to GND.

Careful PC board layout minimizes crosstalk in DAC registers, the reference, and the digital inputs. Separate analog traces by running ground traces between them. Make sure that high-frequency digital lines are not routed parallel to analog lines.

## AC Considerations Digital Feedthrough

High-speed data at any of the digital input pins can couple through a DAC's internal stray package capacitance and cause noise (digital feedthrough) at the DAC output, even though LDAC and/or CS are held high (see *Typical Operating Characteristics*). Test digital feedthrough by holding LDAC and/or CS high and toggling the digital inputs from all 1s to all 0s.

#### Analog Feedthrough

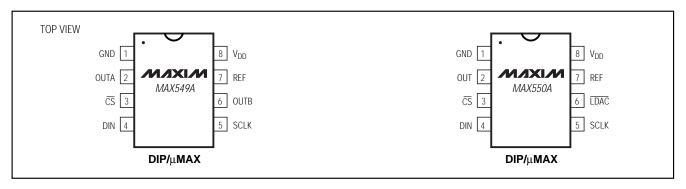
Due to internal stray capacitance, higher frequency analog input signals at REF can couple to the output, even when the input digital code is all 0s. This condition is shown in the MAX549A/MAX550A Reference AC Feedthrough vs. Frequency graph in the *Typical Operating Characteristics*. Test analog feedthrough by setting all DAC outputs to 0V and sweeping REF.

Table 6. Analog Output vs. Code

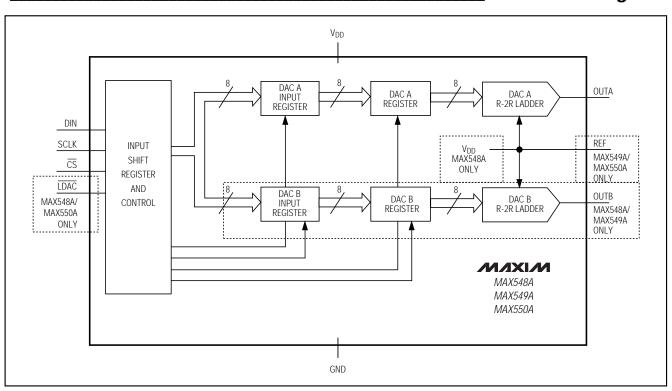
			DAC CO	ANALOG OUTDUT (V)					
D7	D6	D5	D4	D3	D2	D1	D0	ANALOG OUTPUT (V)	
1	1	1	1	1	1	1	1	+V <sub>REF</sub> (255 / 256)	
1	0	0	0	0	0	0	1	+V <sub>REF</sub> (129 / 256)	
1	0	0	0	0	0	0	0	+V <sub>REF</sub> (128 / 256) = +V <sub>REF</sub> / 2	
0	1	1	1	1	1	1	1	+V <sub>REF</sub> (127 / 256)	
0	0	0	0	0	0	0	1	+V <sub>REF</sub> (1 / 256)	
0	0	0	0	0	0	0	0	0	

Note: 1LSB = V<sub>REF</sub> x 2<sup>-8</sup> = V<sub>REF</sub>(1 / 256); ANALOG OUTPUT = +V<sub>REF</sub>(I / 256), where I = Integer Value of Digital Input.

### Pin Configurations (continued)



### Functional Diagram



### \_Ordering Information (continued)

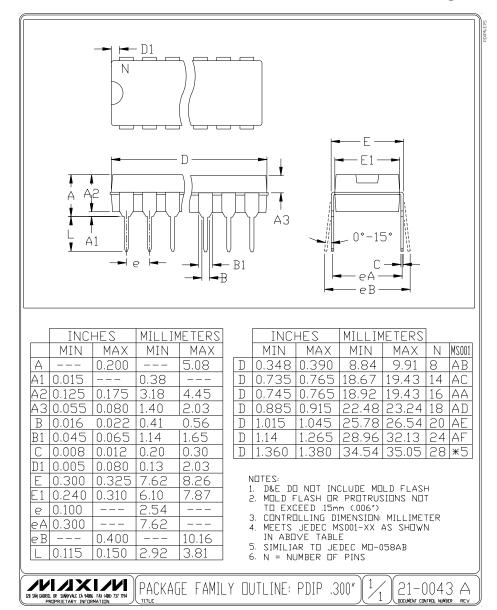
PART	TEMP. RANGE	PIN-PACKAGE
MAX549ACPA	0°C to +70°C	8 Plastic DIP
MAX549ACUA	0°C to +70°C	8 µMAX
MAX549AC/D	0°C to +70°C	Dice*
MAX549AEPA	-40°C to +85°C	8 Plastic DIP
MAX549AEUA	-40°C to +85°C	8 µMAX
MAX550ACPA	0°C to +70°C	8 Plastic DIP
MAX550ACUA	0°C to +70°C	8 µMAX
MAX550AC/D	0°C to +70°C	Dice*
MAX550AEPA	-40°C to +85°C	8 Plastic DIP
MAX550AEUA	-40°C to +85°C	8 μMAX

<sup>\*</sup>Dice are specified at  $T_A = +25$ °C, DC parameters only.

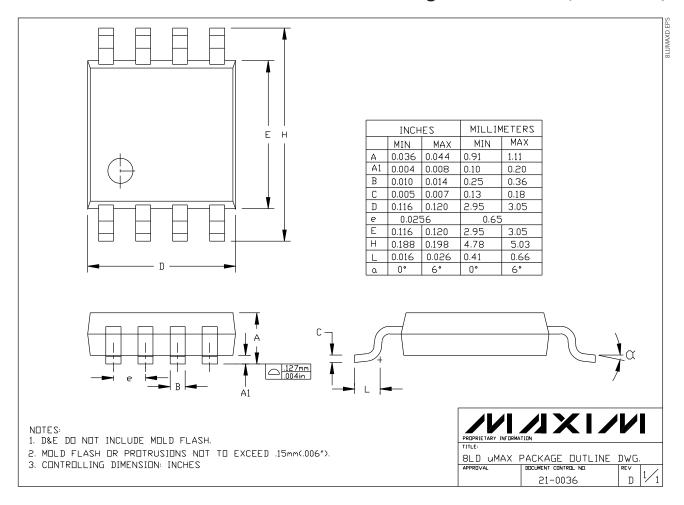
### \_Chip Information

TRANSISTOR COUNT: 1562

\_Package Information



\_Package Information (continued)



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