

Serial-in / Parallel-out Driver Series

4-input Serial-in / Parallel-out Drivers

BU2152FS

Description

BU2152FS is a CMOS output driver. It incorporates a built-in shift register and a latch circuit to turn on a maximum of 24 output by a 4-wire interface, linked to a microcontroller.

A CMOS output can provides maximum 25mA current.

Features

- Possible to drive LED directly
- 24bit parallel output

Pin Configurations

(Top View) VSS 1 32 VDD CLK 2 31 CLB **VSS** 30 STB 29 DATA SO P1 28 P24 27 P23 P2 26 P22 P3 25 P21 8 P4 9 24 P20 P5 P6 23 P19 P7 11 22 P18 P8 21 P17 Р9 20 P16 P10 19 P15 18 P14 P11 17 P13 P12 |16

SSOP-A32

Key Specifications

Power supply voltage range:
 Output voltage:
 Operating temperature range:
 2.7V to 5.5V
 0V to V_{DD}
 25°C to ±25°C

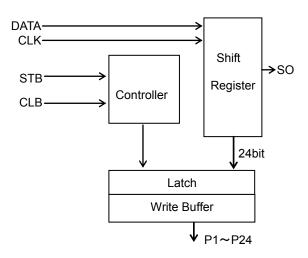
■ Operating temperature range: -25°C to +85°C

Package SSOP-A32

W(Typ) x D(Typ) x H(Max) 13.60mm x 7.80mm x 2.01mm



Block Diagrams



Pin Descriptions

	ı	ı					
Pin No.	Pin Name	I/O	Function				
1	VSS	-	Ground				
2	CLK	I	Serial Clock Input				
3	VSS	-	Ground				
4	DATA	I	Serial Data Input				
5	P1						
6	P2						
7	P3						
8	P4						
9	P5						
10	P6						
11	P7						
12	P8						
13	P9						
14	P10						
15	P11						
16	P12	0	Parallel Data Output				
17	P13	0					
18	P14						
19	P15						
20	P16						
21	P17						
22	P18						
23	P19						
24	P20						
25	P21						
26	P22						
27	P23						
28	P24						
29	SO	0	Serial Data Output				
30	STB	I	Strobe Signal Input (active Low)				
31	CLB	I	Clear Signal Input (active Low)				
32	VDD	-	Power Supply				

Absolute Maximum Ratings

Parameter	Symbol	Limits	Unit
Supply Voltage	V_{DD}	-0.3 to +7.0	V
Input Voltage	V _{IN}	V _{SS} -0.3 to V _{DD} +0.3	V
Output Voltage	Vo	V _{SS} -0.3 to V _{DD} +0.3	V
Total output current	ΣΙο	55	mA
Operating Temperature Range	T _{opr}	-25 to +85	ů
Storage Temperature	T _{stg}	-55 to +125	°C
Power Dissipation	P _D	0.76 ^(Note 1)	W

⁽Note 1) Derate by 7.6mW/°C when operating above T_A =25°C (when mounted in ROHM's standard board).

Caution: Operating the IC over the absolute maximum ratings may damage the IC. The damage can either be a short circuit between pins or an open circuit between pins and the internal circuitry. Therefore, it is important to consider circuit protection measures, such as adding a fuse, in case the IC is operated over the absolute maximum ratings.

Recommended Operating Conditions (T_A =25°C, V_{SS}=0V)

Dorometer	Symbol	Limits			Unit	Condition
Parameter		Min	Тур	Max	Unit	Condition
Power Supply Voltage	V_{DD}	2.7	-	5.5	V	(Note 2)
Output Voltage	Vo	0	-	V_{DD}	V	-
Input rise time	t _r	-	-	1	μs	applied to CLK,DATA,STB,CLB pins ^(Note 3)
Input fall time	t _f	-	_	1	μs	pins ^(Note 3)

⁽Note 2) Set "L" to CLB pin during power up. Set "H" to CLB pin after power is stable.

When V_{DD} become equal to or less than 2.2V, set "L" to CLB pin to clear the latch circuit.

(Note 3) The input signal transition should be linear. Noise shouldn't be on these input pins as there is no hysteresis countermeasure on them.

The length of power and ground lines should be as short as possible and the bypass capacitor should be as close to the IC as possible so that the ground noise caused by the current in its operation don't cause any undesirable data errors.

The rise and fall times had better be smaller than the specified limits.

Electrical Characteristics (Unless otherwise specified V_{DD}=5V, V_{SS}=0V, T_A =25°C)

Daramatar	Symbol	Limits			Cymbol	Limita
Parameter		Min	Тур	Min	Symbol	Limits
Input High-level Voltage	V _{IH}	2.0	-	-	V	-
Input Low-level Voltage	V _{IL}	-	-	0.6	V	-
		V _{DD} -1.5	-	-	V	I _{OH} =-25mA
Output Hi-level Voltage	V _{OH}	V _{DD} -1.0	-	-		I _{OH} =-15mA
		V _{DD} -0.5	-	-		I _{OH} =-10mA
	V _{OL}	-	-	1.5	V	I _{OL} =+25mA
Output Low-level Voltage		-	-	1.0		I _{OL} =+15mA
		-	-	0.8		I _{OL} =+10mA
Input High-level Leak Current	I _{IH}	-	-	1	μA	
Input Low-level Leak Current	I _{IL}	-	-	1	μA	
Quiescent Current	I _{DD}	-	-	5	μΑ	V _{IL} =V _{SS} , V _{IH} =V _{DD} , OUTPUT:OPEN

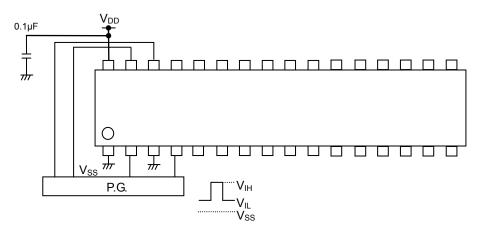
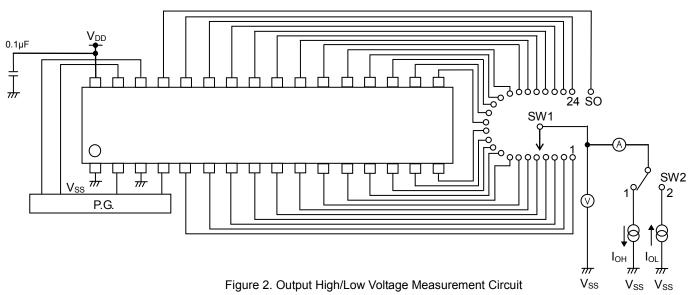


Figure 1. Input High/Low Voltage Measurement Circuit



Test condition

 V_{OL} : Set all data "Low". SW2="2", SW1="1" to"24",SO. V_{OH} : Set all data "High". SW2="1", SW1="1" to"24",SO.

Switching Characteristics (Unless otherwise specified V_{DD}=5V, V_{SS}=0V, T_A =25°C)

Doromotor	Cymah al	Limit			l lm:t	Condition
Parameter	Symbol	Min	Min	Min	Unit	Condition
Maximum Clock Frequency	f _{MAX}	5	-	-	MHz	-
Setup Time 1	t _{SU1}	20	-	-	ns	DATA-CLK
Hold Time 1	t _{HD1}	20	-	-	ns	CLK-DATA
Setup Time 2	t _{SU2}	30	-	-	ns	STB-CLK
Hold Time 2	t _{HD2}	30	-	-	ns	CLK-STB
Setup Time 3	t _{SU3}	30	-	-	ns	CLB-CLK
Hold Time 3	t _{HD3}	30	-	-	ns	CLK-CLB
Setup Time 4	t _{SU4}	30	-	-	ns	STB-CLB
Hold Time 4	t _{HD4}	30	-	-	ns	CLB-STB
Output Delay Time 1	t _{PD1}	-	-	100	ns	CLK-P1 to P24,C _L =50pF
Output Delay Time 2	t _{PD2}	-	-	80	ns	STB-P1 to P24,C _L =50pF
Output Delay Time 3	t _{PD3.}	-	-	80	ns	CLB-P1 to P24,C _L =50pF

Switching Time Test Circuit

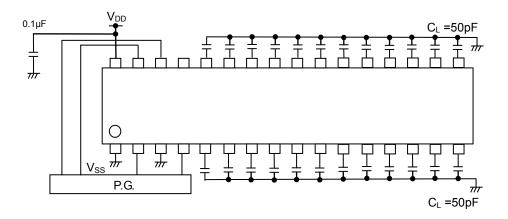
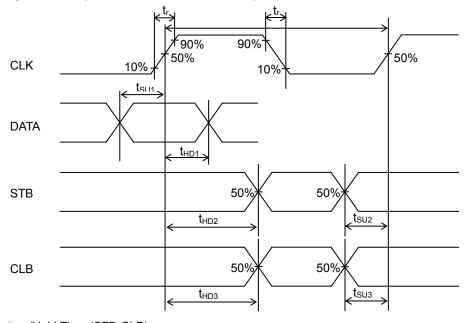


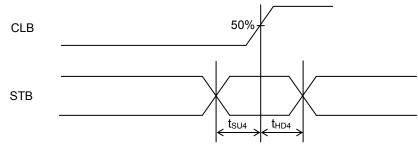
Figure 3. Switching Time Test Circuit

Switching Time Test Waveform

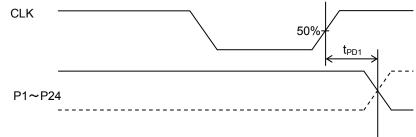
Set-up/Hold Time (DATA-CLK,STB-CLK,CLB-CLK)



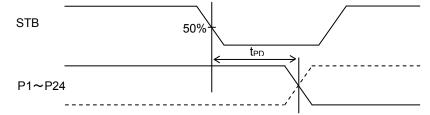
Set-up/Hold Time (STB-CLB)



Output Delay Time (CLK- P1 to P24)



Output Delay Time (STB- P1 to P24)



Output Delay Time (CLB- P1 to P24)

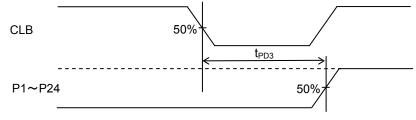


Figure 4. Switching Time Test Waveform

Timing Chart

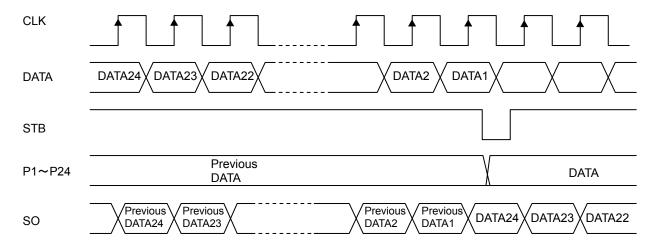


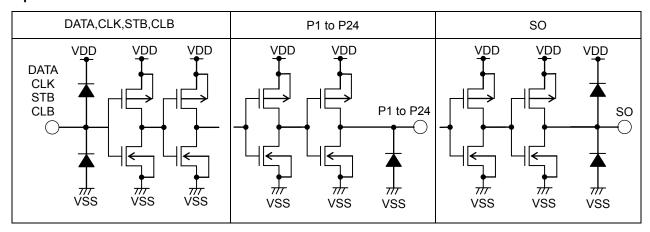
Figure 5. Timing Chart

- 1. After the power is turned on and the voltage is stabilized, STB should be activated, after clocking 24 data bits into the DATA terminal.
- 2. P1 to P24 parallel output data of the shift register is set after the 24th clock by the LCK.
- 3. Since the STB is a level trigger latch, data is retained in the "H" section and renewed in the "L" section of the STB
- 4. The final stage data of the shift register is outputted to the SO by synchronizing with the rise time of the CLK.

[Truth Table]

Input			Function			
CLK	STB	CLB	Function			
×	×	L	All the data of the latch circuit are set to "H" (data of shift register does not change), all the parallel outputs are "H".			
	Н	Н	Serial data of DATA pin are latched to the shift register. At this time, the data of the latch circuit does not change.			
L			The data of the shift register are transferred to the latch circuit, and the data of			
Н		. I н	the latch circuit are outputted from the parallel output pin.			
<u>-</u>		П	The data of the shift register shifts 1bit, and the data of the latch circuit and parallel output also change.			

I/O Equivalence Circuits



Power Dissipation

Power dissipation(total loss) indicates the power that can be consumed by IC at T_A =25°C(normal temperature). IC is heated when it consumed power, and the temperature of IC chip becomes higher than ambient temperature. The temperature that can be accepted by IC chip depends on circuit configuration, manufacturing process, and consumable power is limited. Power dissipation is determined by the temperature allowed in IC chip(maximum junction temperature) and thermal resistance of package(heat dissipation capability). The maximum junction temperature is typically equal to the maximum value in the storage temperature range. Heat generated by consumed power of IC radiates from the mold resin or lead frame of the package. The parameter which indicates this heat dissipation capability(hardness of heat release)is called thermal resistance, represented by the symbol θ_{JA} (°C/W). The temperature of IC inside the package can be estimated by this thermal resistance. Figure 6 shows the model of thermal resistance of the package. Thermal resistance θ_{JA} , ambient temperature T_{A} , maximum junction temperature T_{Jmax} , and power dissipation P_{D} can be calculated by the equation below: $\theta_{JA} = (T_{Jmax} - T_{A}) / P_{D}$ (°C/W)

Derating curve in Figure 7 indicates power that can be consumed by IC with reference to ambient temperature. Power that can be consumed by IC with reference to ambient temperature. Power that can be consumed by IC begins to attenuate at certain ambient temperature. This gradient is determined by thermal resistance θ_{JA} . Thermal resistance θ_{JA} depends on chip size, power consumption, package, ambient temperature, package condition, wind velocity, etc even when the same of package is used. Thermal reduction curve indicates a reference value measured at a specified condition.

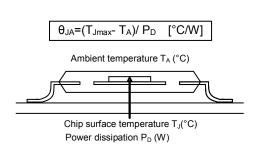


Figure 6. Thermal resistance

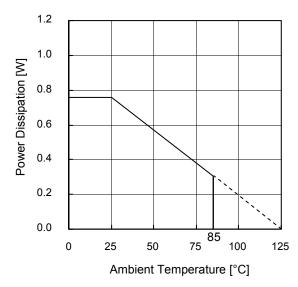


Figure 7. Derating curve of BU2152FS

Operational Notes

1. Reverse Connection of Power Supply

Connecting the power supply in reverse polarity can damage the IC. Take precautions against reverse polarity when connecting the power supply, such as mounting an external diode between the power supply and the IC's power supply pins.

2. Power Supply Lines

Design the PCB layout pattern to provide low impedance supply lines. Separate the ground and supply lines of the digital and analog blocks to prevent noise in the ground and supply lines of the digital block from affecting the analog block. Furthermore, connect a capacitor to ground at all power supply pins. Consider the effect of temperature and aging on the capacitance value when using electrolytic capacitors.

3. Ground Voltage

Ensure that no pins are at a voltage below that of the ground pin at any time, even during transient condition.

4. Ground Wiring Pattern

When using both small-signal and large-current ground traces, the two ground traces should be routed separately but connected to a single ground at the reference point of the application board to avoid fluctuations in the small-signal ground caused by large currents. Also ensure that the ground traces of external components do not cause variations on the ground voltage. The ground lines must be as short and thick as possible to reduce line impedance.

5. Thermal Consideration

Should by any chance the power dissipation rating be exceeded the rise in temperature of the chip may result in deterioration of the properties of the chip. In case of exceeding this absolute maximum rating, increase the board size and copper area to prevent exceeding the Pd rating.

6. Recommended Operating Conditions

These conditions represent a range within which the expected characteristics of the IC can be approximately obtained. The electrical characteristics are guaranteed under the conditions of each parameter.

7. Inrush Current

When power is first supplied to the IC, it is possible that the internal logic may be unstable and inrush current may flow instantaneously due to the internal powering sequence and delays, especially if the IC has more than one power supply. Therefore, give special consideration to power coupling capacitance, power wiring, width of ground wiring, and routing of connections.

8. Operation Under Strong Electromagnetic Field

Operating the IC in the presence of a strong electromagnetic field may cause the IC to malfunction.

9. Testing on Application Boards

When testing the IC on an application board, connecting a capacitor directly to a low-impedance output pin may subject the IC to stress. Always discharge capacitors completely after each process or step. The IC's power supply should always be turned off completely before connecting or removing it from the test setup during the inspection process. To prevent damage from static discharge, ground the IC during assembly and use similar precautions during transport and storage.

Operational Notes - continued

10. Inter-pin Short and Mounting Errors

Ensure that the direction and position are correct when mounting the IC on the PCB. Incorrect mounting may result in damaging the IC. Avoid nearby pins being shorted to each other especially to ground, power supply and output pin. Inter-pin shorts could be due to many reasons such as metal particles, water droplets (in very humid environment) and unintentional solder bridge deposited in between pins during assembly to name a few.

11. Unused Input Pins

Input pins of an IC are often connected to the gate of a MOS transistor. The gate has extremely high impedance and extremely low capacitance. If left unconnected, the electric field from the outside can easily charge it. The small charge acquired in this way is enough to produce a significant effect on the conduction through the transistor and cause unexpected operation of the IC. So unless otherwise specified, unused input pins should be connected to the power supply or ground line.

12. Regarding the Input Pin of the IC

In the construction of this IC, P-N junctions are inevitably formed creating parasitic diodes or transistors. The operation of these parasitic elements can result in mutual interference among circuits, operational faults, or physical damage. Therefore, conditions which cause these parasitic elements to operate, such as applying a voltage to an input pin lower than the ground voltage should be avoided. Furthermore, do not apply a voltage to the input pins when no power supply voltage is applied to the IC. Even if the power supply voltage is applied, make sure that the input pins have voltages within the values specified in the electrical characteristics of this IC.

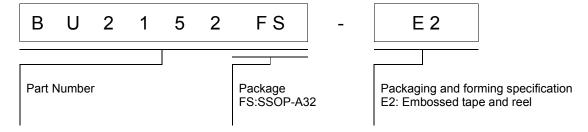
13. Ceramic Capacitor

When using a ceramic capacitor, determine the dielectric constant considering the change of capacitance with temperature and the decrease in nominal capacitance due to DC bias and others.

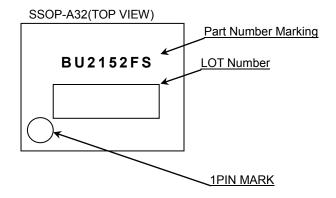
14. Area of Safe Operation (ASO)

Operate the IC such that the output voltage, output current, and power dissipation are all within the Area of Safe Operation (ASO).

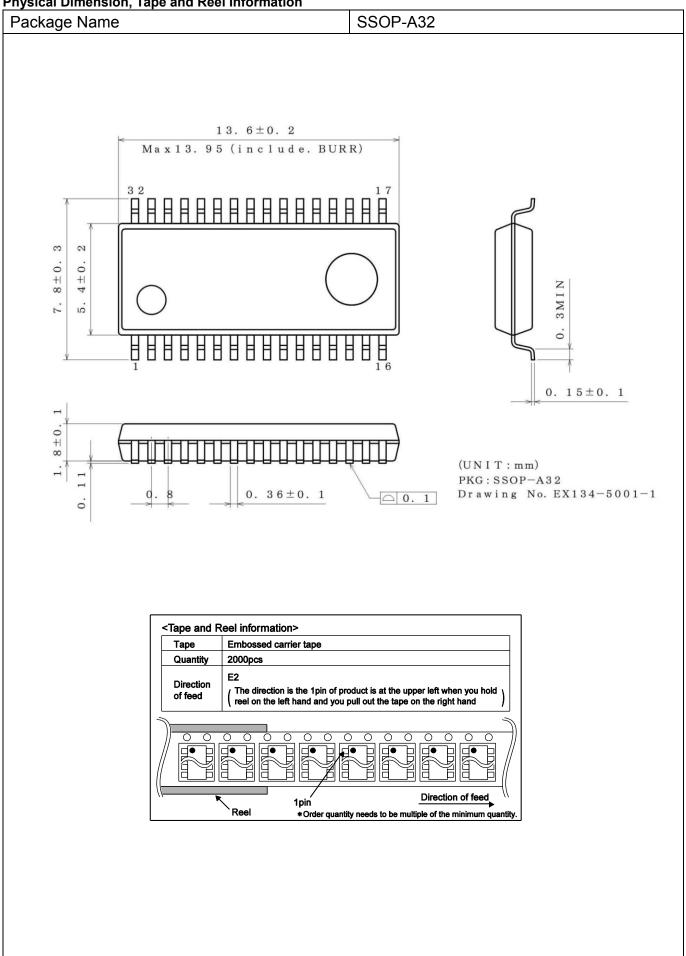
Ordering Information



Marking Diagrams



Physical Dimension, Tape and Reel Information



Revision History

· <u> </u>					
Date	Revision	Changes			
18.Apr.2014	001	New Release			
24.Aug.2015	002	Add the total output current at absolute maximum ratings. Add the input rise time & the input fall time at recommended operating conditions. Renewal of the Note No. Correction of the power dissipation & the derating curve			

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(Note1) Medical Equipment Classification of the Specific Applications

JAPAN	USA	EU	CHINA	
CLASSⅢ	CLASSⅢ	CLASS II b	CL A C C TT	
CLASSIV	CLASSIII	CLASSⅢ	CLASSIII	

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- 7. De-rate Power Dissipation (Pd) depending on Ambient temperature (Ta). When used in sealed area, confirm the actual ambient temperature.
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- 9. ROHM shall not be in any way responsible or liable for failure induced under deviant condition from what is defined in this document.

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