

**Vishay Siliconix** 

# 50 A VRPower<sup>®</sup> Integrated Power Stage

#### DESCRIPTION

The SiC638 are integrated power stage solutions optimized for synchronous buck applications to offer high current, high efficiency, and high power density performance. Packaged in Vishay's proprietary 5 mm x 5 mm MLP package, SiC638 enables voltage regulator designs to deliver up to 50 A continuous current per phase.

The internal power MOSFETs utilizes Vishay's state-of-the-art Gen IV TrenchFET technology that delivers industry benchmark performance to significantly reduce switching and conduction losses.

The SiC638 incorporate an advanced MOSFET gate driver IC that features high current driving capability, adaptive dead-time control, an integrated bootstrap Schottky diode, a thermal warning (THWn) that alerts the system of excessive junction temperature, and zero current detection to improve light load efficiency. The drivers are also compatible with a wide range of PWM controllers and supports tri-state PWM, 3.3 V / 5 V PWM logic.

#### FEATURES

- Thermally enhanced PowerPAK<sup>®</sup> MLP55-31L package
- Vishay's Gen IV MOSFET technology and a low side MOSFET with integrated Schottky diode
- Delivers up to 50 A continuous current
- High efficiency performance
- High frequency operation up to 1.5 MHz
- Power MOSFETs optimized for 19 V input stage
- 3.3 V / 5 V PWM logic with tri-state and hold-off
- Zero current detect control for light load efficiency improvement
- Low PWM propagation delay (< 20 ns)
- Faster disable
- Thermal monitor flag
- Under voltage lockout for V<sub>CIN</sub>
- Material categorization: for definitions of compliance please see <u>www.vishay.com/doc?99912</u>

#### **APPLICATIONS**

- Multi-phase VRDs for computing, graphics card and memory
- Intel IMVP-8 VRPower delivery

   V<sub>CORE</sub>, V<sub>GRAPHICS</sub>, V<sub>SYSTEM AGENT</sub> Skylake, Kabylake
   platforms
  - -V<sub>CCGI</sub> for Apollo Lake platforms
- Up to 24 V rail input DC/DC VR modules

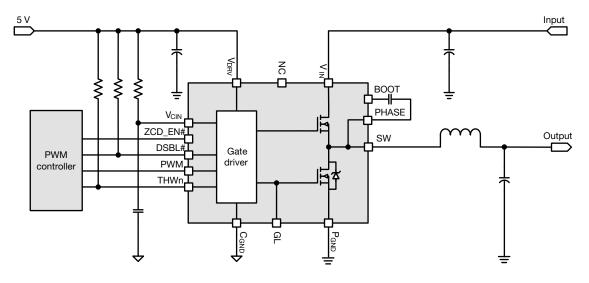
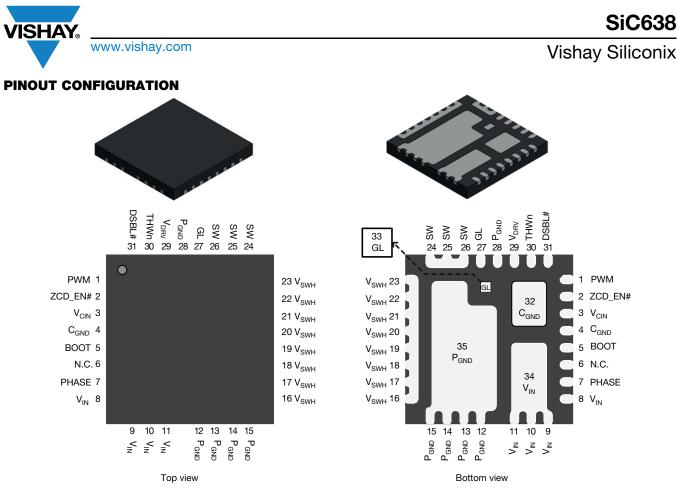


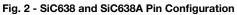
Fig. 1 - SiC638 and SiC638A Typical Application Diagram

#### **TYPICAL APPLICATION DIAGRAM**







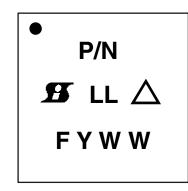


PIN CONFIG	URATION	
PIN NUMBER	NAME	FUNCTION
1	PWM	PWM input logic
2	ZCD_EN#	The ZCD_EN# pin enables or disables diode emulation. When ZCD_EN# is LOW, diode emulation is allowed. When ZCD_EN# is HIGH, continuous conduction mode is forced
3	V <sub>CIN</sub>	Supply voltage for internal logic circuitry
4, 32	C <sub>GND</sub>	Signal ground
5	BOOT	High side driver bootstrap voltage
6	N.C.	Not connected internally, can be left floating or connected to ground
7	PHASE	Return path of high side gate driver
8 to 11, 34	V <sub>IN</sub>	Power stage input voltage. Drain of high side MOSFET
12 to 15, 28, 35	P <sub>GND</sub>	Power ground
16 to 26	SW	Phase node of the power stage
27, 33	GL	Low side MOSFET gate signal
29	V <sub>DRV</sub>	Supply voltage for internal gate driver
30	THWn	Thermal warning open drain output
31	DSBL#	Disable pin. Active low

ORDERING INFORMATION						
PART NUMBER	PACKAGE	MARKING CODE	OPTION			
SiC638CD-T1-GE3	PowerPAK MLP55-31L	SiC638	5 V PWM optimized			
SiC638ACD-T1-GE3	PowerPAK MLP55-31L	SiC638A	3.3 V PWM optimized			
SiC638DB		Reference board				

#### PART MARKING INFORMATION

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- = Pin 1 Indicator
- P/N = Part Number Code
- 🖪 🛛 = Siliconix Logo
- $\triangle$  = ESD Symbol
- F = Assembly Factory Code
- Y = Year Code
- WW = Week Code
  - LL = Lot Code

ELECTRICAL PARAMETER	CONDITIONS	LIMIT	UNIT	
Input voltage	V <sub>IN</sub>	-0.3 to +30		
Control logic supply voltage	V <sub>CIN</sub>	-0.3 to +7		
Drive supply voltage	V <sub>DRV</sub>	-0.3 to +7		
Switch node (DC voltage)	N/	-0.3 to +30		
Switch node (AC voltage) (1)	V <sub>SWH</sub>	-7 to +35	1	
BOOT voltage (DC voltage)	N N	35	V	
BOOT voltage (AC voltage) (2)	V <sub>BOOT</sub>	40		
BOOT to PHASE (DC voltage)		-0.3 to +7		
BOOT to PHASE (AC voltage) (3)	VBOOT-PHASE	-0.3 to +8		
All logic inputs and outputs (PWM, DSBL#, and THWn)		-0.3 to V <sub>CIN</sub> + 0.3		
Max. operating junction temperature	TJ	150		
Ambient temperature	T <sub>A</sub>	-40 to +125	°C	
Storage temperature	T <sub>stg</sub>	-65 to +150		
Fleetweetstie discharge protection	Human body model, JESD22-A114	3000	V	
Electrostatic discharge protection	Charged device model, JESD22-C101	1000	- V	

Notes

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings
only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the
specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability

<sup>(1)</sup> The specification values indicated "AC" is V<sub>SWH</sub> to P<sub>GND</sub> -8 V (< 20 ns, 10  $\mu$ J), min. and 35 V (< 50 ns), max.

<sup>(2)</sup> The specification value indicates "AC voltage" is  $V_{BOOT}$  to  $P_{GND}$ , 40 V (< 50 ns) max.

<sup>(3)</sup> The specification value indicates "AC voltage" is V<sub>BOOT</sub> to V<sub>PHASE</sub>, 8 V (< 20 ns) max.

RECOMMENDED OPERATING RANGE							
ELECTRICAL PARAMETER	MINIMUM	TYPICAL	MAXIMUM	UNIT			
Input voltage (V <sub>IN</sub> )	2.7	-	24				
Drive supply voltage (V <sub>DRV</sub> )	4.5	5	5.5	v			
Control logic supply voltage (V <sub>CIN</sub> )	4.5	5	5.5	v			
BOOT to PHASE (V <sub>BOOT-PHASE</sub> , DC voltage)	4	4.5	5.5	-			
Thermal resistance from junction to ambient	-	10.6	-	°C/W			
Thermal resistance from junction to case	-	1.6	-	C/W			

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	OVMDO:	TEST CONDITION	LIMITS			11611-	
PARAMETER	SYMBOL	TEST CONDITION	MIN.	TYP.	MAX.	UNIT	
POWER SUPPLY							
		$V_{DSBL\#} = 0 V$ , no switching, $V_{PWM} = FLOAT$	-	5	-		
Control logic supply current	I <sub>VCIN</sub>	$V_{DSBL\#} = 5 V$ , no switching, $V_{PWM} = FLOAT$	-	300	-	μA	
		$V_{DSBL\#} = 5 V$ , f <sub>S</sub> = 300 kHz, D = 0.1	-	350	-		
		f <sub>S</sub> = 300 kHz, D = 0.1	-	9	14		
Drive events		f <sub>S</sub> = 1 MHz, D = 0.1	-	30	-	mA	
Drive supply current	I <sub>VDRV</sub>	$V_{DSBL\#} = 0 V$ , no switching	-	15	-		
		$V_{DSBL\#} = 5 V$ , no switching	-	55	-	μA	
BOOTSTRAP SUPPLY							
Bootstrap diode forward voltage	V <sub>F</sub>	$I_F = 2 \text{ mA}$			0.4	V	
PWM CONTROL INPUT (SiC638)							
Rising threshold	V <sub>TH_PWM_R</sub>		-	-	4.2		
Falling threshold	V <sub>TH_PWM_F</sub>		0.72	-	-	v	
Tri-state voltage	V <sub>TRI_FLOAT</sub>	$V_{PWM} = FLOAT$	-	2.3	-	v	
Tri-state window	V <sub>TRI_WINDOW</sub>		1.38	-	3		
Tri-state rising threshold hysteresis	V <sub>HYS_TRI_R</sub>		-	225	-		
Tri-state falling threshold hysteresis	V <sub>HYS_TRI_F</sub>		-	325	-	mV	
		$V_{PWM} = 5 V, DSBL# = high$	-	-	350	- μA	
	I <sub>PWM</sub>	$V_{PWM} = 5 V$ , DSBL# = low	-	-	1		
PWM input current		$V_{PWM} = 0 V, DSBL# = high$	-	-	-350		
		$V_{PWM} = 0 V, DSBL# = low$	-	-	-1		
PWM CONTROL INPUT (SiC638A)				•			
Rising threshold	V <sub>TH_PWM_R</sub>		-	-	2.7		
Falling threshold	V <sub>TH_PWM_F</sub>		0.72	-	-	v	
Tri-state Voltage	V <sub>TRI_FLOT</sub>	$V_{PWM} = FLOAT$	-	1.8	-	v	
Tri-state window	V <sub>TRI_WINDOW</sub>		1.38	-	1.95		
Tri-state rising threshold hysteresis	V <sub>HYS_TRI_R</sub>		-	250	-		
Tri-state falling threshold hysteresis	V <sub>HYS_TRI_F</sub>		-	300	-	mV	
		V <sub>PWM</sub> = 3.3 V, DSBL# = high	-	-	225		
DW/M input ourrent		$V_{PWM} = 3.3 V, DSBL# = Iow$	-	-	1		
PWM input current	IPWM	$V_{PWM} = 0 V, DSBL# = high$	-	-	-225	μA	
		$V_{PWM} = 0 V, DSBL# = low$	-	-	-1		
TIMING SPECIFICATIONS							
Tri-state to GH/GL rising propagation delay	t <sub>PD_TRI_R</sub>		-	30	-		
Tri-state hold-off time	t <sub>TSHO</sub>		-	130	-		
GH - turn off propagation delay	t <sub>PD_OFF_GH</sub>		-	15	-	]	
GH - turn on propagation delay (dead time rising)	t <sub>PD_ON_GH</sub>	No load, see fig. 4	-	10	-		
GL - turn off propagation delay	tPD_OFF_GL		-	13	-	ns	
GL - turn on propagation delay (dead time falling)	t <sub>PD_ON_GL</sub>		-	10	-		
DSBL# Lo to GH/GL falling propagation delay	t <sub>PD_DSBL#_F</sub>	Fig. 5	-	15	-	]	
			1		1	-1	

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ELECTRICAL SPECIFICA (DSBL# = ZCD_EN# = 5 V, V		and V <sub>CIN</sub> = 5 V, T <sub>A</sub> = 25 °C)					
DADAMETED	CYMPOL	TEST CONDITION		LIMITS			
PARAMETER	SYMBOL TEST CONDITION		MIN.	TYP.	MAX.	AX. UNIT	
DSBL# ZCD_EN# INPUT							
DSBL# logic input voltage	V <sub>IH_DSBL#</sub>	Input logic high	2	-	-		
DSBL# logic input voltage	V <sub>IL_DSBL#</sub>	Input logic low	-	-	0.8	v	
ZCD ENI# logic input voltage	V <sub>IH_ZCD_EN#</sub>	Input logic high	2	-	-	- V	
ZCD_EN# logic input voltage	V <sub>IL_ZCD_EN#</sub>						
PROTECTION							
Linder veltage leekeut	Maria	V <sub>CIN</sub> rising, on threshold	-	3.7	4.1	v	
Under voltage lockout	V <sub>UVLO</sub>	V <sub>CIN</sub> falling, off threshold	2.7	3.1	-	v	
Under voltage lockout hysteresis	V <sub>UVLO_HYST</sub>		-	575	-	mV	
THWn flag set <sup>(2)</sup>	T <sub>THWn_SET</sub>		-	160	-		
THWn flag clear <sup>(2)</sup>	T <sub>THWn_CLEAR</sub>		-	135	-	°C	
THWn flag hysteresis <sup>(2)</sup>	T <sub>THWn_HYST</sub>		-	25	-		
THWn output low	V <sub>OL_THWn</sub>	I <sub>THWn</sub> = 2 mA	-	0.02	-	V	

Notes

<sup>(1)</sup> Typical limits are established by characterization and are not production tested

<sup>(2)</sup> Guaranteed by design

#### **DETAILED OPERATIONAL DESCRIPTION**

#### **PWM Input with Tri-state Function**

The PWM input receives the PWM control signal from the VR controller IC. The PWM input is designed to be compatible with standard controllers using two state logic (H and L) and advanced controllers that incorporate tri-state logic (H, L and tri-state) on the PWM output. For two state logic, the PWM input operates as follows. When PWM is driven above V<sub>PWM TH B</sub> the low side is turned OFF and the high side is turned ON. When PWM input is driven below V<sub>PWM TH F</sub> the high side is turned OFF and the low side is turned ON. For tri-state logic, the PWM input operates as previously stated for driving the MOSFETs when PWM is logic high and logic low. However, there is a third state that is entered as the PWM output of tri-state compatible controller enters its high impedance state during shut-down. The high impedance state of the controller's PWM output allows the SiC638 and SiC638A to pull the PWM input into the tri-state region (see definition of PWM logic and Tri-State, fig. 4). If the PWM input stays in this region for the Tri-state Hold-Off Period, tTSHO, both high side and low side MOSFETs are turned OFF. The function allows the VR phase to be disabled without negative output voltage swing caused by inductor ringing and saves a Schottky diode clamp. The PWM and tri-state regions are separated by hysteresis to prevent false triggering. The SiC638A incorporates PWM voltage thresholds that are compatible with 3.3 V logic and the SiC638 thresholds are compatible with 5 V logic.

#### Disable (DSBL#)

In the low state, the DSBL# pin shuts down the driver IC and disables both high side and low side MOSFETs. In this state, standby current is minimized. If DSBL# is left unconnected, an internal pull-down resistor will pull the pin to  $C_{\rm GND}$  and shut down the IC.

#### Diode Emulation Mode (ZCD\_EN#)

When ZCD\_EN# pin is driven below  $V_{IL_ZCD_EN#}$ . diode emulation mode is enabled. If the PWM signal switches below  $V_{TH_PWM_F}$  then the LS MOSFET is under control of the ZCD (zero crossing detect) comparator. If, after the internal blanking delay, the inductor current becomes less than or = 0 the low side is turned OFF. Light load efficiency is improved by avoiding discharge of output capacitors. If both high side and low side MOSFETs are required to be turned OFF, regardless of inductor current, the PWM input should be tri-stated.

#### Thermal Shutdown Warning (THWn)

The THWn pin is an open drain signal that flags the presence of excessive junction temperature. Connect with a maximum of 20 k $\Omega$ , to V<sub>CIN</sub>. An internal temperature sensor detects the junction temperature. The temperature threshold is 160 °C. When this junction temperature is exceeded the THWn flag is set. When the junction temperature drops below 135 °C the device will clear the THWn signal. The SiC638 and SiC638A do not stop operation when the flag is set. The decision to shutdown must be made by an external thermal control function.

#### Voltage Input (VIN)

This is the power input to the drain of the high side power MOSFET. This pin is connected to the high power intermediate BUS rail.

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#### Switch Node (V<sub>SWH</sub> and PHASE)

The switch node, V<sub>SWH</sub>, is the circuit power stage output. This is the output applied to the power inductor and output filter to deliver the output for the buck converter. The PHASE pin is internally connected to the switch node V<sub>SWH</sub>. This pin is to be used exclusively as the return pin for the BOOT capacitor. A 20 k $\Omega$  resistor is connected between GH (the high side gate) and PHASE to provide a discharge path for the HS MOSFET in the event that V<sub>CIN</sub> goes to zero while V<sub>IN</sub> is still applied.

#### Ground Connections (C<sub>GND</sub> and P<sub>GND</sub>)

 $\mathsf{P}_{\mathsf{GND}}$  (power ground) should be externally connected to  $\mathsf{C}_{\mathsf{GND}}$  (signal ground). The layout of the printed circuit board should be such that the inductance separating  $\mathsf{C}_{\mathsf{GND}}$  and  $\mathsf{P}_{\mathsf{GND}}$  is minimized. Transient differences due to inductance effects between these two pins should not exceed 0.5 V

#### Control and Drive Supply Voltage Input (VDRV, VCIN)

 $V_{CIN}$  is the bias supply for the gate drive control IC.  $V_{DRV}$  is the bias supply for the gate drivers. It is recommended to separate these pins through a resistor. This creates a low pass filtering effect to avoid coupling of high frequency gate drive noise into the IC.

#### Bootstrap Circuit (BOOT)

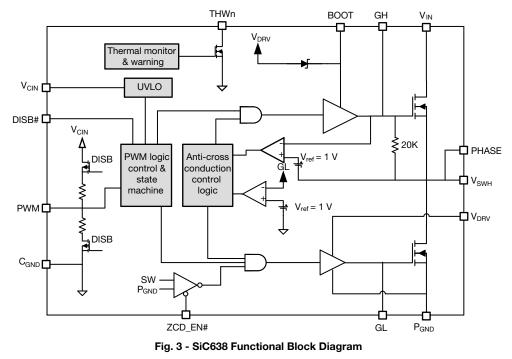
The internal bootstrap diode and an external bootstrap capacitor form a charge pump that supplies voltage to the BOOT pin. An integrated bootstrap diode is incorporated so that only an external capacitor is necessary to complete the bootstrap circuit. Connect a boot strap capacitor with one leg tied to BOOT pin and the other tied to PHASE pin.

#### Shoot-Through Protection and Adaptive Dead Time

The SiC638 and SiC638A have an internal adaptive logic to avoid shoot through and optimize dead time. The shoot through protection ensures that both high side and low side MOSFETs are not turned ON at the same time. The adaptive dead time control operates as follows. The high side and low side gate voltages are monitored to prevent the MOSFET turning ON from tuning ON until the other MOSFET's gate voltage is sufficiently low (< 1 V). Built in delays also ensure that one power MOSFET is completely OFF, before the other can be turned ON. This feature helps to adjust dead time as gate transitions change with respect to output current and temperature.

#### Under Voltage Lockout (UVLO)

During the start up cycle, the UVLO disables the gate drive holding high side and low side MOSFET gates low until the supply voltage rail has reached a point at which the logic circuitry can be safely activated. The SiC638, SiC638A also incorporates logic to clamp the gate drive signals to zero when the UVLO falling edge triggers the shutdown of the device. As an added precaution, a 20 k $\Omega$  resistor is connected between GH (the high side gate) and PHASE to provide a discharge path for the HS MOSFET.



#### FUNCTIONAL BLOCK DIAGRAM

**SiC638** 



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DEVICE TRUTH T	DEVICE TRUTH TABLE							
DSBL#	ZCD_EN#	PWM	GH	GL				
Open	Х	Х	L	L				
L	Х	Х	L	L				
Н	L	L	L	H, I <sub>L</sub> > 0 A L, I <sub>L</sub> < 0 A				
Н	L	Н	Н	L				
Н	L	mid	L	L				
Н	Н	L	L	Н				
Н	Н	Н	Н	L				
Н	Н	mid	L	L				

#### **PWM TIMING DIAGRAM**

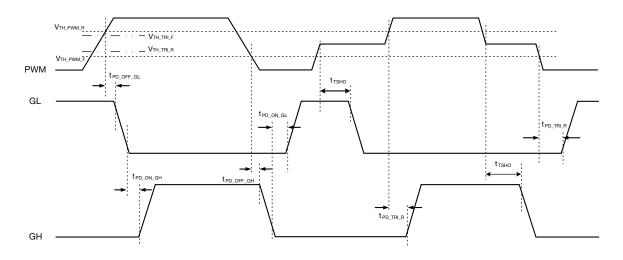


Fig. 4 - Definition of PWM Logic and Tri-state

#### DSBL# PROPAGATION DELAY

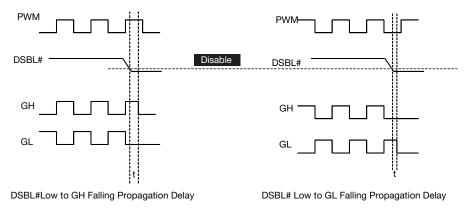


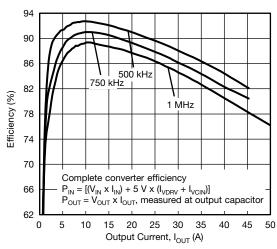
Fig. 5 - DSBL# Falling Propagation Delay

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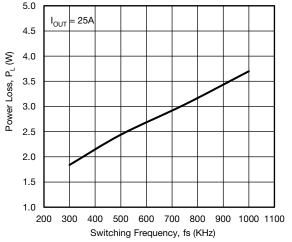
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#### **ELECTRICAL CHARACTERISTICS**

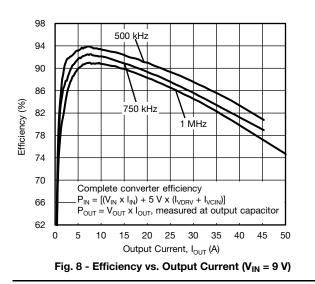
Test condition:  $V_{IN} = 13 \text{ V}$ , DSBL# =  $V_{DRV} = V_{CIN} = 5 \text{ V}$ , ZCD\_EN# = 5 V,  $V_{OUT} = 1 \text{ V}$ ,  $L_{OUT} = 250 \text{ nH}$  (DCR = 0.32 m $\Omega$ ),  $T_A = 25 \text{ °C}$ , natural convection cooling (All power loss and normalized power loss curves show SiC638 and SiC638A losses only unless otherwise stated)











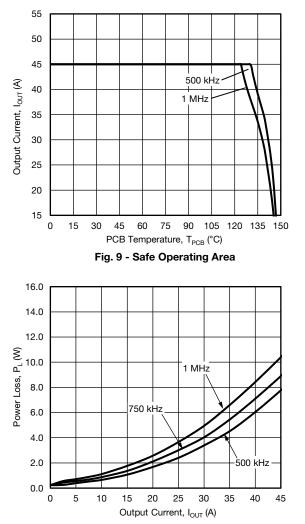
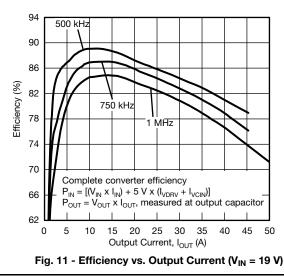


Fig. 10 - Power Loss vs. Output Current (V<sub>IN</sub> = 12.6 V)



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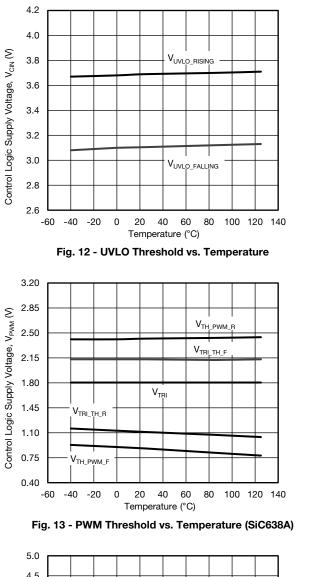
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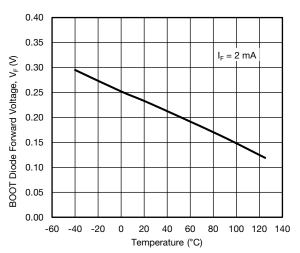
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#### **ELECTRICAL CHARACTERISTICS**

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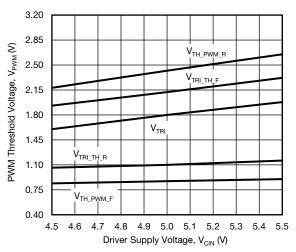
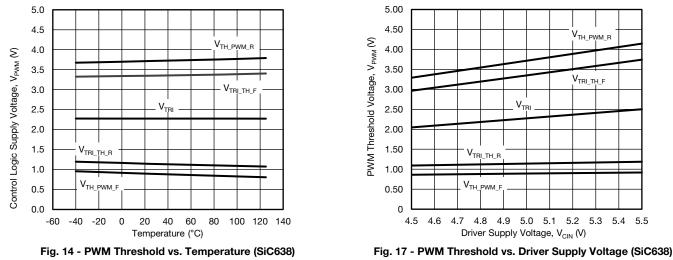


Fig. 16 - PWM Threshold vs. Driver Supply Voltage (SiC638A)



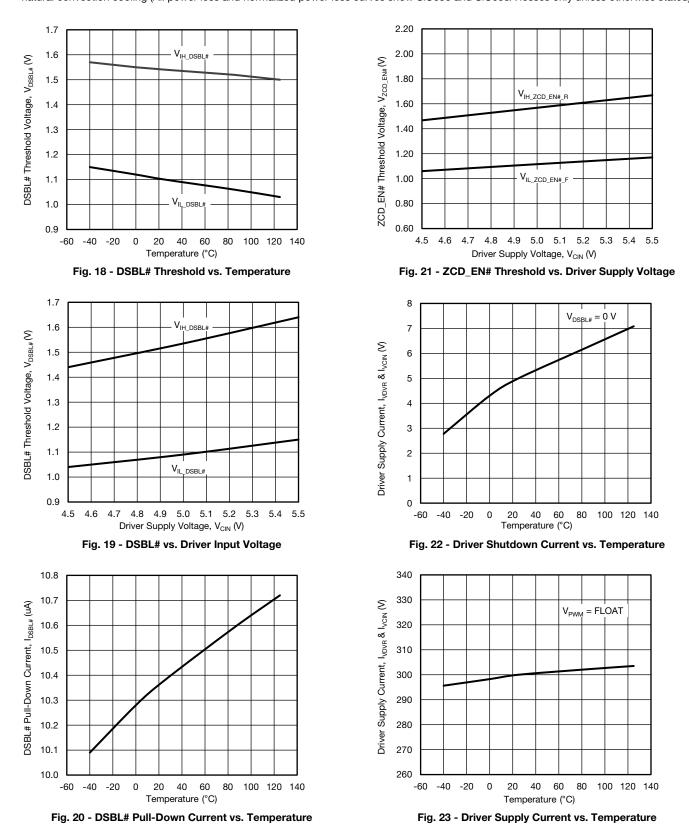
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#### **ELECTRICAL CHARACTERISTICS**



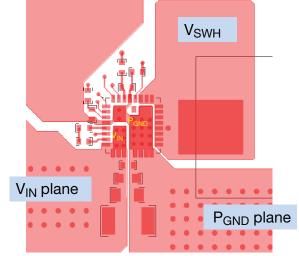
Test condition:  $V_{IN} = 13 \text{ V}$ , DSBL# =  $V_{DRV} = V_{CIN} = 5 \text{ V}$ , ZCD\_EN# = 5 V,  $V_{OUT} = 1 \text{ V}$ ,  $L_{OUT} = 250 \text{ nH}$  (DCR = 0.32 m $\Omega$ ),  $T_A = 25 ^{\circ}$ C, natural convection cooling (All power loss and normalized power loss curves show SiC638 and SiC638A losses only unless otherwise stated)

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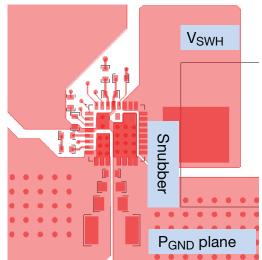
#### PCB LAYOUT RECOMMENDATIONS

Step 1: V<sub>IN</sub>/GND Planes and Decoupling



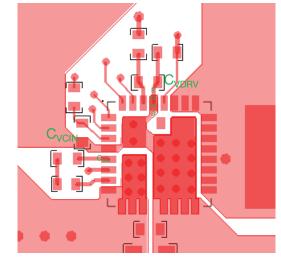
- 1. Layout  $V_{\text{IN}}$  and  $P_{\text{GND}}$  planes as shown above
- 2. Ceramic capacitors should be placed right between  $V_{\rm IN}$  and  $P_{\rm GND},$  and very close to the device for best decoupling effect
- 3. Difference values / packages of ceramic capacitors should be used to cover entire decoupling spectrum e.g. 1210, 0805, 0603 and 0402
- 4. Smaller capacitance value, closer to device  $V_{\text{IN}}\ \text{pin(s)}$  better high frequency noise absorbing

#### Step 2: V<sub>SWH</sub> Plane



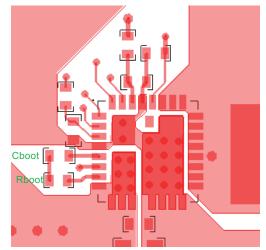
- 1. Connect output inductor to DrMOS with large plane to lower the resistance
- 2. If any snubber network is required, place the components as shown above and the network can be placed at bottom

#### Step 3: V<sub>CIN</sub>/V<sub>DRV</sub> Input Filter



- 1. The  $V_{CIN}/V_{DRV}$  input filter ceramic cap should be placed very close to IC. It is recommended to connect two caps separately.
- 2. C<sub>VCIN</sub> cap should be placed between pin 3 and pin 4 (C<sub>GND</sub> of driver IC) to achieve best noise filtering.
- 3.  $C_{\rm VDRV}$  cap should be placed between pin 28 ( ${\rm P_{GND}}$  of driver IC) and pin 29 to provide maximum instantaneous driver current for low side MOSFET during switching cycle
- 4. For connecting C<sub>VCIN</sub> analog ground, it is recommended to use large plane to reduce parasitic inductance.

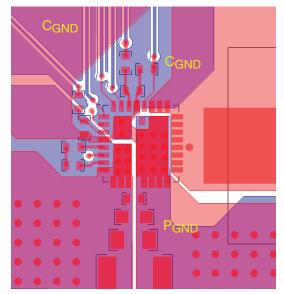
#### Step 4: BOOT Resistor and Capacitor Placement



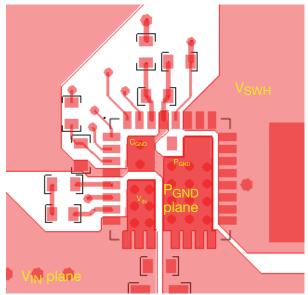
- 1. These components need to be placed very close to IC, right between PHASE (pin 7) and BOOT (pin 5).
- 2. To reduce parasitic inductance, chip size 0402 can be used.

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#### Step 5: Signal Routing



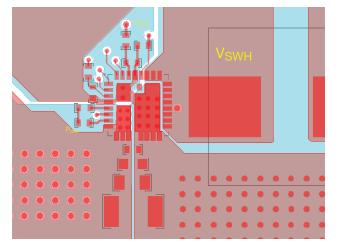
- 1. Route the PWM / ZCD\_EN# / DSBL# / THWn signal traces out of the top left corner next DrMOS pin 1.
- 2. PWM signal is very important signal, both signal and return traces need to pay special attention of not letting this trace cross any power nodes on any layer.
- 3. It is best to "shield" traces form power switching nodes, e.g. V<sub>SWH</sub>, to improve signal integrity.
- 4. GL (pin 27) has been connected with GL pad internally and does not need to connect externally.



Step 6: Adding Thermal Relief Vias

- 1. Thermal relief vias can be added on the  $V_{\rm IN}$  and  $P_{\rm GND}$  pads to utilize inner layers for high current and thermal dissipation.
- 2. To achieve better thermal performance, additional vias can be put on  $V_{\rm IN}$  plane and  $P_{\rm GND}$  plane.
- 3.  $V_{\text{SWH}}$  pad is a noise source and not recommended to put vias on this plane.
- 4. 8 mil drill for pads and 10 mils drill for plane can be the optional via size. Vias on pad may drain solder during assembly and cause assembly issue. Please consult with the assembly house for guideline.

#### Step 7: Ground Connection



- 1. It is recommended to make single connection between  $C_{GND}$  and  $P_{GND}$  and this connection can be done on top layer.
- 2. It is recommended to make the whole inner 1 layer (next to top layer) ground plane and separate them into  $C_{GND}$  and  $P_{GND}$  plane.
- 3. These ground planes provide shielding between noise source on top layer and signal trace on bottom layer.



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#### Multi-Phases VRPower PCB Layout

Following is an example for 6 phase layout. As can be seen, all the VRPower stages are lined in X-direction compactly with decoupling caps next to them. The inductors are placed as close as possible to the SiC638 and SiC638A to minimize the PCB copper loss. Vias are applied on all PADs ( $V_{IN}$ ,  $P_{GND}$ ,  $C_{GND}$ ) of the SiC638 and SiC638A to ensure that both electrical and thermal performance are excellent. Large copper planes are used for all the high current loops, such as  $V_{IN}$ ,  $V_{SWH}$ ,  $V_{OUT}$  and  $P_{GND}$ . These copper planes are duplicated in other layers to minimize the inductance and resistance. All the control signals are routed from the SiC638 and SiC638A to a controller placed to the north of the power stage through inner layers to avoid the overlap of high current loops. This achieves a compact design with the output from the inductors feeding a load located to the south of the design as shown in the figure.

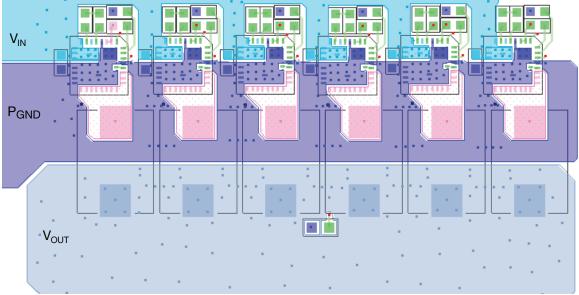


Fig. 24 - Multi - Phase VRPower Layout Top View

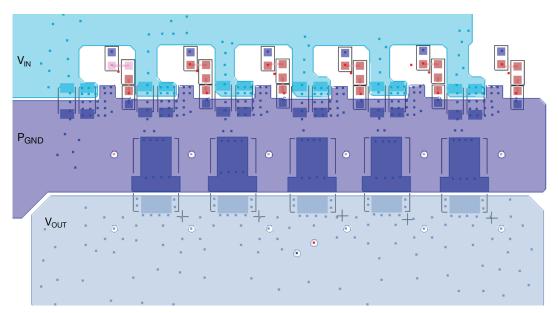


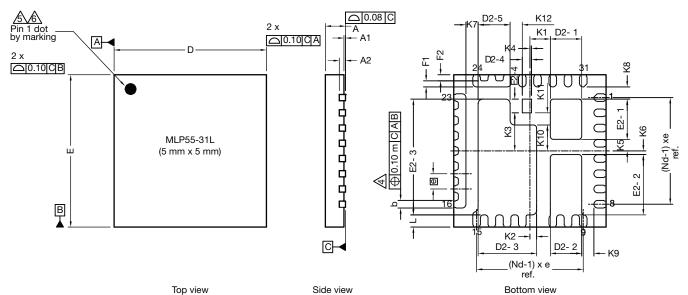
Fig. 25 - Multi - Phase VRPower Layout Bottom View

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# PowerPAK<sup>®</sup> MLP55-31L Case Outline



Side view

Bottom view

DIM.		MILLIMETERS		INCHES		
	MIN.	NOM.	MAX.	MIN.	NOM.	MAX.
A <sup>(8)</sup>	0.70	0.75	0.80	0.027	0.029	0.031
A1	0.00	-	0.05	0.000	-	0.002
A2		0.20 ref.			0.008 ref.	
b <sup>(4)</sup>	0.20	0.25	0.30	0.008	0.010	0.012
D	4.90	5.00	5.10	0.193	0.196	0.200
е		0.50 BSC			0.019 BSC	
E	4.90	5.00	5.10	0.193	0.196	0.200
L	0.35	0.40	0.45	0.013	0.015	0.017
N <sup>(3)</sup>		32			32	
Nd <sup>(3)</sup>	8				8	
Ne <sup>(3)</sup>		8		8		
D2-1	0.98	1.03	1.08	0.039	0.041	0.043
D2-2	0.98	1.03	1.08	0.039	0.041	0.043
D2-3	1.87	1.92	1.97	0.074	0.076	0.078
D2-4		0.30 BSC		0.012 BSC		
D2-5	1.00	1.05	1.10	0.039	0.041	0.043
E2-1	1.27	1.32	1.37	0.050	0.052	0.054
E2-2	1.93	1.98	2.03	0.076	0.078	0.080
E2-3	3.75	3.80	3.82	0.148	0.150	0.152
E2-4		0.45 BSC			0.018 BSC	
F1		0.20 BSC		0.008 BSC		
F2		0.20 BSC			0.008 BSC	
K1		0.67 BSC		0.026 BSC		
K2	0.22 BSC			0.008 BSC		
K3	1.25 BSC			0.049 BSC		
K4	0.05 BSC				0.002 BSC	
K5	0.38 BSC				0.015 BSC	
K6		0.12 BSC			0.005 BSC	

Revision: 24-Oct-16

1 For technical questions, contact: powerictechsupport@vishay.com

## **Package Information**



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DIM.	MILLIMETERS			INCHES				
	MIN.	NOM.	MAX.	MIN.	NOM.	MAX.		
K7		0.40 BSC			0.016 BSC			
K8		0.40 BSC 0.016 BSC						
K9	0.40 BSC 0.016 BSC							
K10		0.85 BSC 0.033 BSC						
K11		0.40 BSC			0.016 BSC			
K12	0.40 BSC			0.016 BSC				
ECN: T16-0644-Re DWG: 6025	ev. E, 24-Oct-16							

Notes

1. Use millimeters as the primary measurement

2. Dimensioning and tolerances conform to ASME Y14.5M. - 1994

3. N is the number of terminals,

Nd is the number of terminals in X-direction, and

Ne is the number of terminals in Y-direction

 $\underline{/\!\!\!\!A}$ Dimension b applies to plated terminal and is measured between 0.20 mm and 0.25 mm from terminal tip

🖄 The pin #1 identifier must be existed on the top surface of the package by using indentation mark or other feature of package body

Exact shape and size of this feature is optional

7. Package warpage max. 0.08 mm

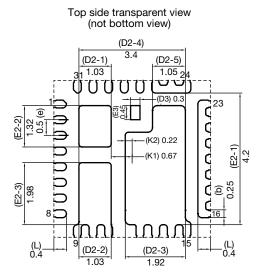
Applied only for terminals

### **PAD** Pattern

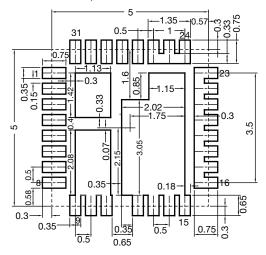


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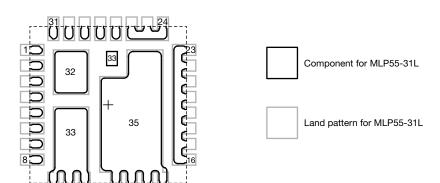
### Recommended Land Pattern PowerPAK<sup>®</sup> MLP55-31L for SiC620, SiC620A



Land pattern for MLP55-31L



All dimensions in millimeters



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